

Miscellaneous thoughts on the midterm.

★ Remember with the true-false that every statement is in its full generality. If a statement holds for some but not all instances, it is false.

★ Remember the difference between a coordinate vector and the vector it represents – in the standard basis the two often look very much alike but they are not the same, and with a nonstandard basis they will generally be quite different.

★ To prove two sets are equal it is often useful to prove in two steps; that is, containment each direction.

★ A different way to look at matrix multiplication which may be helpful:

Each row of  $AB$  is a linear combination of the rows of  $B$  with coefficients from the corresponding row of  $A$ :

If the second row of  $A$  is 02000, the second row of  $AB$  will be twice the second row of  $B$ .

If the fourth row of  $A$  is 10001, the fourth row of  $AB$  will be the sum of the first and fifth rows of  $B$ .

Likewise, each column of  $AB$  is a linear combination of columns of  $A$  with coefficients from the corresponding column of  $B$ :

If the first column of  $B$  is 01010, the first column of  $AB$  will be the sum of the second and fourth columns of  $A$ .

If the third column of  $B$  is 20002, the third column of  $AB$  will be twice the sum of the first and fifth columns of  $A$ .

Those examples could all have come from the following matrix multiplication:

$$\begin{pmatrix} 0 & 0 & 0 & 1 & 0 \\ 0 & 2 & 0 & 0 & 0 \\ 0 & 0 & 3 & 0 & 0 \\ 1 & 0 & 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 0 & 1 & 2 \\ 1 & 1 & 0 \\ 0 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 1 & 0 \\ 2 & 2 & 0 \\ 0 & 3 & 0 \\ 0 & 2 & 4 \end{pmatrix}.$$

This gives also a different way to look at the identity matrix: since the first row and column of  $I_n$  are both  $10\dots 0$ , the first row of  $I_n B$  will be equal to the first row of  $B$  and the first column of  $A I_n$  will be equal to the first column of  $A$ . Likewise as you move from 1 to  $n$ , for both rows and columns, and hence multiplication on either side will not change  $A$  or  $B$ .

★ Big hint for 2.3 #17:

Projections are the answer (see the bottom of p. 76). Note that  $T^2$  here means  $T$  composed with  $T$ . Verify it by (the easy direction) showing every projection is equal to its composition with itself, and (the harder direction) everything which is equal to its composition with itself is a projection. For the latter you can use the hint in the book, saying that  $x = x - T(x) + T(x)$ ; by assumption on  $T$ , this is the sum of an element of  $N(T)$  and an element of  $\{y : T(y) = y\}$ . You need to show that the latter is a subspace, and that it intersects  $N(T)$  only at  $\theta$ . Then  $V$  is the direct sum, and  $T$  is just the projection along  $N(T)$  onto  $\{y : T(y) = y\}$ .

★ For 2.2 #11, the matrix shown there is simply meant to convey the idea that the first  $k$  entries of the bottom  $n - k$  rows are all zero. For #15, remember functions (and linear transformations, therefore) are defined entirely by what they do to their inputs.  $aT + U$  is the function which takes any  $x$  to  $aT(x) + U(x)$ , by definition, and that is all you need to know about it.