

**Exercise 1:** Some things about the classical Lie algebras.

(1) For each of the following types, give a basis  $B$  which has exactly  $r$  diagonal matrices and is otherwise as workable as possible. In particular, keep symmetry, so that if  $x \in B$  then  $x^T \in B$ . Express elements as sums of elementary matrices  $E_{ij}$  (the matrix with a 1 in the  $(i, j)$  position and 0's elsewhere. Clearly, we're choosing a basis for  $V$  in the process. A form on  $V$  defined by a matrix  $J$  is defined by  $\langle u, v \rangle = u^T J v$ . Let  $I_r$  be the  $r \times r$  identity matrix.

(a) **Type  $A_r$ .** For  $r \geq 1$ , give a basis for  $\mathfrak{sl}_{r+1}$ , and verify that  $\dim(\mathfrak{sl}_{r+1}) = r(r+2)$ .

(b) **Type  $C_r$ .** For  $r \geq 1$ , put the form on  $V = \mathbb{C}^{2r}$  given by  $J = \begin{pmatrix} 0 & I_r \\ -I_r & 0 \end{pmatrix}$ .

(\*) Verify that  $\langle, \rangle$  is skew symmetric, i.e.  $\langle u, v \rangle = -\langle v, u \rangle$ .

(\*) Verify that if  $\mathfrak{sp}_{2r} = \{x \in \mathfrak{sl}(V) \mid \langle xu, v \rangle = -\langle u, xv \rangle\}$ , then  $\mathfrak{sp}_{2r}$  is in fact closed ( $\langle, \rangle$  is bilinear, so you only need to check  $[\cdot, \cdot]$ .)

(\*) Give a basis for  $\mathfrak{sp}_{2r}$ , and verify that  $\dim(\mathfrak{sp}_{2r}) = r(2r+1)$ . (Break each  $x \in \mathfrak{sp}_{2r}$  into the four  $r \times r$  matrices that  $J$  effect independently, (see below) and get conditions on each of them)

(c) **Type  $D_r$ .** For  $r \geq 2$ , put the form on  $V = \mathbb{C}^{2r}$  given by  $J = \begin{pmatrix} 0 & I_r \\ I_r & 0 \end{pmatrix}$ .

(\*) Verify that  $\langle, \rangle$  is symmetric, i.e.  $\langle u, v \rangle = \langle v, u \rangle$ .

(\*) Verify that if  $\mathfrak{so}_{2r} = \{x \in \mathfrak{sl}(V) \mid \langle xu, v \rangle = -\langle u, xv \rangle\}$ , then  $\mathfrak{so}_{2r}$  is closed.

(\*) Give a basis for  $\mathfrak{so}_{2r}$ , and verify that  $\dim(\mathfrak{so}_{2r}) = r(2r-1)$ . (Break each  $x \in \mathfrak{so}_{2r}$  into the four  $r \times r$  matrices that  $J$  effects independently, (see below) and get conditions on each of them)

(d) **Type  $B_r$ .** For  $r \geq 1$ , put the form on  $V = \mathbb{C}^{2r+1}$  given by  $J = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & I_r \\ 0 & I_r & 0 \end{pmatrix}$ . Give a

basis for  $\mathfrak{so}_{2r+1}$ , and verify that  $\dim(\mathfrak{so}_{2r+1}) = r(2r+1)$ . (Break each  $x \in \mathfrak{so}_{2r+1}$  into the nine blocks that  $J$  effects independently (see below) and get conditions on each of them.)

(2) As mentioned in class,  $B_1, C_1, C_2, D_1, D_2$ , and  $D_3$  are either not distinct from, or decompose into direct sums of Lie algebras from amongst.

$$\{A_r\}_{r \geq 1} \sqcup \{B_r\}_{r \geq 2} \sqcup \{C_r\}_{r \geq 3} \sqcup \{D_r\}_{r \geq 4}$$

Verify this for any 4 of these 6 Lie algebras by expressing them in terms of the others.

Decompositions of elements for  $\mathfrak{g}$  of each type.

$$\begin{array}{c} C_r, D_r \\ \left( \begin{array}{|c|c|} \hline X & Y \\ \hline Y' & Z \\ \hline \end{array} \right) \end{array} \quad \begin{array}{c} B_r \\ \left( \begin{array}{|c|c|c|} \hline a & \mathbf{b} & \mathbf{c} \\ \hline \mathbf{b}' & X & Y \\ \hline \mathbf{c}' & Y' & Z \\ \hline \end{array} \right) \end{array}$$