

# Operator Algebras for Closure of Dynamical Systems

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# Motivation

## Original system

$$x_{n+1} = \phi(x_n, Z(y_n))$$

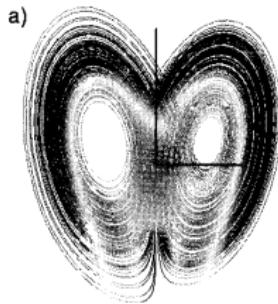
$$y_{n+1} = \psi(x_n, y_n)$$

## Parameterized system

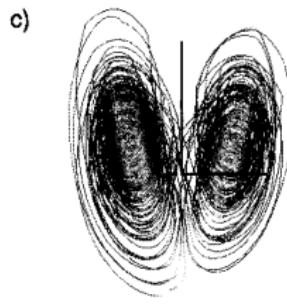
$$x_{n+1} = \tilde{\phi}(x_n, \tilde{Z}(\tilde{y}_n))$$

$$\tilde{y}_{n+1} = \tilde{\psi}(x_n, \tilde{y}_n)$$

## Lorenz 63 system



## Stochastic closure



Palmer (2001), QJRMS.

## Axioms of quantum mechanics

1. States are **density operators**, i.e., positive, trace-class operators  $\rho : \mathcal{H} \rightarrow \mathcal{H}$  on a Hilbert space  $\mathcal{H}$ , with  $\text{tr } \rho = 1$ .

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3. Measurement expectation and probability:

$$\mathbb{E}_\rho A = \text{tr}(\rho A), \quad \mathbb{P}_\rho(\Omega) = \mathbb{E}_\rho(E(\Omega)), \quad A = \int_{\mathbb{R}} a dE(a).$$

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5. State conditioning by quantum effects:

$$\rho|_e = \frac{\sqrt{e}\rho\sqrt{e}}{\text{tr}(\sqrt{e}\rho\sqrt{e})}, \quad 0 < e \leq I.$$

## Embedding into a quantum mechanical system

Classical statistical

$\mathcal{P}(M) \xrightarrow{\textcolor{red}{P}} \mathcal{P}(M)$

- $\Phi : M \rightarrow M$ : Dynamical flow with invariant measure  $\mu$ .
- $\mathcal{P}(\mu)$ : Probability densities in  $L^1(\mu)$ .
- $P : \mathcal{P}(\mu) \rightarrow \mathcal{P}(\mu)$ : Transfer operator,  $Pp = p \circ \Phi^{-1}$ .
- $L^\infty(\mu)$ : Algebra of classical observables.
- $U : H \rightarrow H$ : Koopman operator on  $H = L^2(\mu)$ ,  $Uf = f \circ \Phi$ .

## Embedding into a quantum mechanical system

$$\begin{array}{ccc} \text{Classical statistical} & & \mathcal{P}(M) \xrightarrow{\textcolor{red}{P}} \mathcal{P}(M) \\ & \downarrow \Gamma & \downarrow \Gamma \\ \text{Quantum mechanical} & & \mathcal{Q}(H) \xrightarrow{\textcolor{blue}{\mathcal{P}}} \mathcal{Q}(H) \end{array}$$

- Embedding of probability densities into quantum states on  $H$ :

$$\Gamma : \mathcal{P}(M) \rightarrow \mathcal{Q}(H), \quad \Gamma(\nu) = \rho := \langle \nu^{1/2}, \cdot \rangle \nu^{1/2}.$$

- Embedding of observables:  $\pi : L^\infty(\mu) \rightarrow B(H)$ ,  $(\pi f)g = fg$ .
- Unitary evolution:  $\mathcal{P}\rho = U^* \rho U$ .
- Quantum–classical consistency:

$$\mathbb{E}_{P\rho} f = \mathbb{E}_{\mathcal{P}(\Gamma\rho)}(\pi f) \equiv \text{tr}((\mathcal{P}(\Gamma\rho))(\pi f)).$$

## Embedding into a quantum mechanical system

$$\begin{array}{ccc} \text{Classical statistical} & \mathcal{P}(M) & \xrightarrow{\textcolor{red}{P}} \mathcal{P}(M) \\ & \Gamma \downarrow & \downarrow \Gamma \\ \text{Quantum mechanical} & \mathcal{Q}(H) & \xrightarrow{\textcolor{blue}{P}} \mathcal{Q}(H) \\ & \Pi'_L \downarrow & \downarrow \Pi'_L \\ \text{Matrix mechanical} & \mathcal{Q}(H_L) & \xrightarrow{\textcolor{blue}{P}_L} \mathcal{Q}(H_L) \end{array}$$

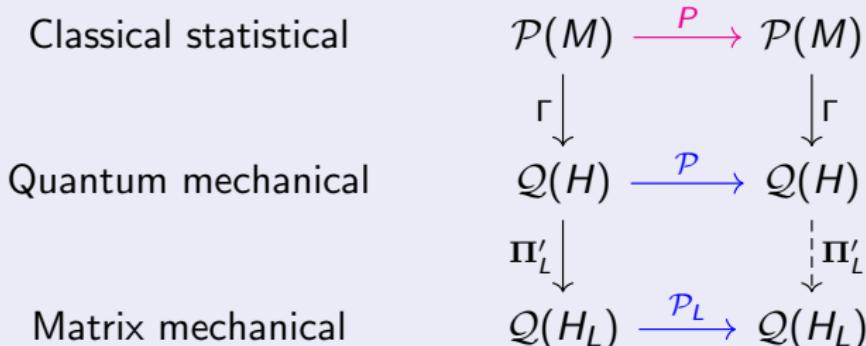
- $H_L \subset H$ : Finite-dimensional approximation space,  $\Pi_L = \text{proj}_{H_L}$ .
- Projection of quantum states:

$$\Pi'_L(\rho) = \rho_L := \frac{\Pi_L \rho \Pi_L}{\text{tr}(\Pi_L \rho \Pi_L)}$$

- Projection of evolution operators:

$$\mathcal{P}_L \rho_L = \frac{U_L^* \rho_L U_L}{\text{tr}(U_L^* \rho_L U_L)}, \quad U_L = \Pi_L U \Pi_L.$$

## Embedding into a quantum mechanical system



### Structure preservation

- Unlike a projection  $\Pi_L \nu$  of a classical probability density, a projected quantum state  $\Pi_L \rho \Pi_L$  is a **positive** operator.
- Embedding into the infinite-dimensional quantum system on  $H$ , and *then* projecting to finite dimensions, allows us to construct positivity-preserving approximation schemes in ways which are not possible in abelian spaces.

## State conditioning by effect-valued feature maps

$$\rho|_{\mathcal{F}(x)} = \frac{\sqrt{\mathcal{F}(x)}\rho\sqrt{\mathcal{F}(x)}}{\text{tr}(\sqrt{\mathcal{F}(x)}\rho\sqrt{\mathcal{F}(x)})}$$

- Observation map:  $Z : M \rightarrow \mathcal{X}$ .
- Kernel on observation space:  $k : \mathcal{X} \times \mathcal{X} \rightarrow [0, 1]$ .
- Feature map:  $F : \mathcal{X} \rightarrow L^\infty(\mu)$ ,  $F(y) = k(y, Z(\cdot))$ .
- Operator-valued feature map:  $\mathcal{F} : \mathcal{X} \rightarrow B(H)$ ,  $\mathcal{F} = \pi \circ F$ .
- Projected feature map:  $\mathcal{F}_L : \mathcal{X} \rightarrow B(H_L)$ ,  $\mathcal{F}_L(x) = \Pi_L \mathcal{F}(x) \Pi_L$ .

## Quantum mechanical closure

### Original system

$$x_{n+1} = \phi(x_n, Z(y_n))$$

$$y_{n+1} = \psi(x_n, y_n)$$

### Parameterized system

$$x_{n+1} = \tilde{\phi}(x_n, \tilde{Z}(\rho_n))$$

$$\rho_{n+1} = \tilde{\psi}(x_n, \rho_n)$$

- Resolved variables:  $x_n \in \mathcal{X}$ .
- Unresolved variables:  $y_n \in \mathcal{Y}$ .
- Fluxes from unresolved variables:  $Z : \mathcal{Y} \rightarrow \mathbb{R}^d$ ,  $Z = (Z_1, \dots, Z_d)$ .
- Surrogate unresolved variables (quantum states):  $\rho_n \in \mathcal{Q}(H_L)$ .
- Parameterized fluxes:  $\tilde{Z} : \mathcal{Q}(H_L) \rightarrow \mathbb{R}^d$ ,  $\tilde{Z} = (\tilde{Z}_1, \dots, \tilde{Z}_d)$ ,

$$\tilde{Z}_k(\rho_n) = \text{tr}(\rho_n(\pi Z_k)).$$

- Evolution map for quantum states:  $\tilde{\psi} : \mathcal{X} \times \mathcal{Q}(H_L) \rightarrow \mathcal{Q}(H_L)$ ,

$$\tilde{\psi}(x_n, \rho_n) = \tilde{\rho}_{n+1}|_{\mathcal{F}(x_{n+1})}, \quad \tilde{\rho}_{n+1} = \mathcal{P}_L \rho_n, \quad x_{n+1} = \tilde{\phi}(x_n, \tilde{Z}(\rho_n)).$$

## Quantum mechanical closure

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**Given:** Samples  $x_0, \dots, x_{N-1} \in \mathcal{X}$ ,  $z_0, \dots, z_{N-1} \in \mathbb{R}^d$  with  $z_n = Z(y_n)$ , along dynamical trajectory of the original system.

- Build data-driven basis  $\{\phi_0, \dots, \phi_{L-1}\}$  of  $H_L$ .
- Compute  $L \times L$  transfer operator matrix  $\mathbf{P} = [P_{ij}]$ ,

$$P_{ij} = \langle \phi_i, P\phi_j \rangle.$$

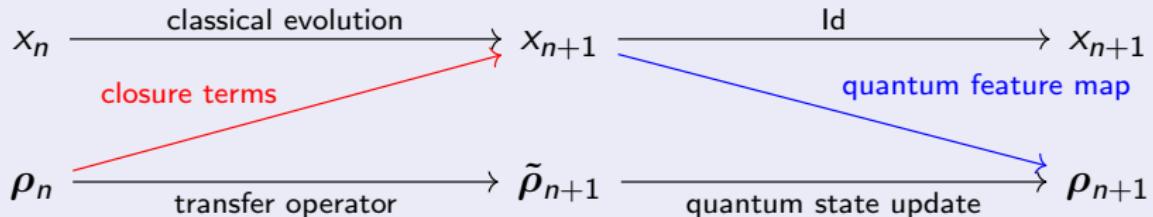
- Compute  $L \times L$  multiplication operator matrices  $\tilde{\mathbf{Z}}_1, \dots, \tilde{\mathbf{Z}}_d$ ,

$$\tilde{\mathbf{Z}}_k = [Z_{k,ij}], \quad Z_{k,ij} = \langle \phi_i, (\pi Z_k) \phi_j \rangle.$$

- Construct matrix-valued feature map,  $\mathbf{F} : \mathcal{X} \rightarrow \mathbb{R}^{L \times L}$ ,

$$\mathbf{F}(x) = [F_{ij}(x)], \quad F_{ij}(x) = \langle \phi_i, \mathcal{F}_L(x) \phi_j \rangle.$$

# Quantum mechanical closure



## Closure algorithm

- ① Compute parameterized fluxes:  $\tilde{z}_n = (\tilde{z}_{n,1}, \dots, \tilde{z}_{n,d})$ ,  $z_{n,k} = \text{tr}(\rho_n \tilde{\mathbf{Z}}_k)$ .
- ② Update resolved variables:  $x_{n+1} = \tilde{\phi}(x_n, z_n)$ .
- ③ Compute prior quantum state:  $\tilde{\rho}_{n+1} = \mathbf{P} \tilde{\rho}_n$ .
- ④ Compute conditional state:  $\rho_{n+1} = \tilde{\rho}_{n+1}|_{\mathcal{F}(x_{n+1})}$ .

## Lorenz 63 (after Palmer 2001)

$$\dot{a}_1 = 2.3 a_1 - 6.2 a_3 - 0.49 a_1 a_2 - 0.57 a_2 a_3$$

$$\dot{a}_2 = -62 - 2.7 a_2 + 0.49 a_1^2 - 0.49 a_3^2 + 0.14 a_1 a_3$$

$$\dot{a}_3 = -0.63 a_1 - 13 a_3 + 0.43 a_1 a_2 + 0.49 a_2 a_3$$

- $(a_1, a_2, a_3)$ : PCA coordinates.
- Resolved variables:  $(a_1, a_2) = x \in \mathcal{X} \equiv \mathbb{R}^2$ .
- Unresolved variables:  $a_3 = y \in \mathcal{Y} \equiv \mathbb{R}$ .
- Flux terms:  $Z : \mathcal{Y} \rightarrow \mathbb{R}$ ,  $Z(a_3) = a_3$ .

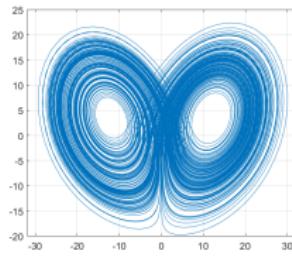
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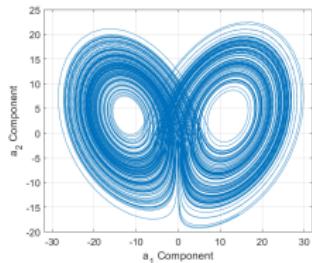
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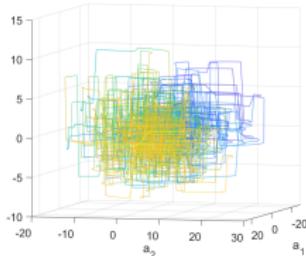
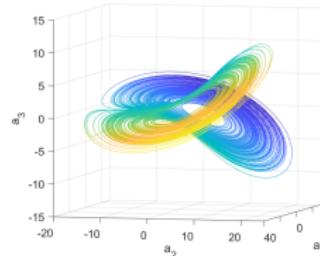
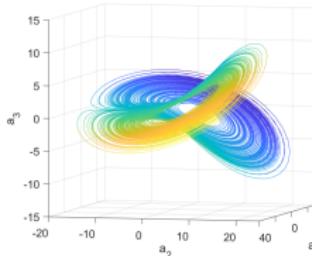
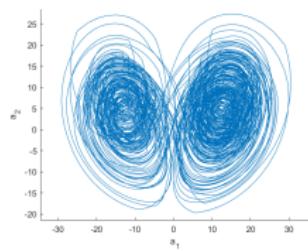
L63 system



QM closure



Gaussian closure

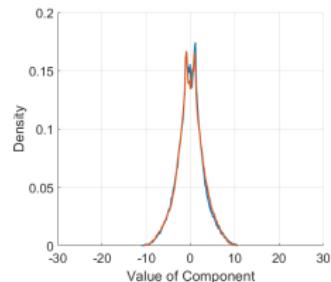
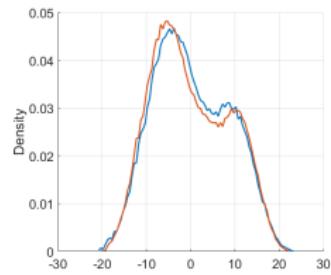
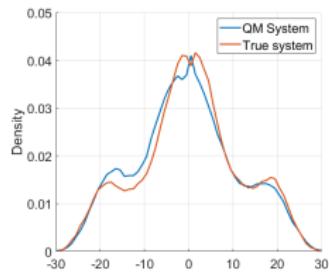
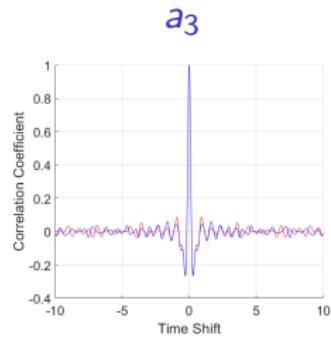
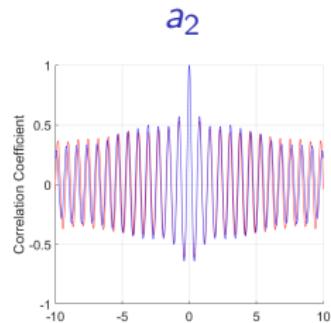
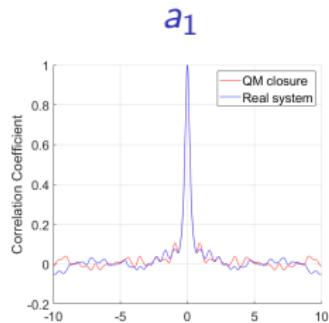


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## Lorenz 96 multiscale (after Fatkullin & Vanden-Eijnden 2004)

$$\dot{x}_k = -x_{k-1}(x_{k-2} - x_{k+1}) - x_k + F + \frac{h_x}{J} \sum_{j=1}^J y_{j,k}$$

$$\dot{y}_{j,k} = \frac{1}{\varepsilon} (-y_{j+1,k}(y_{j+2,k} - y_{j-1,k}) - y_{j,k} + h_y x_k)$$

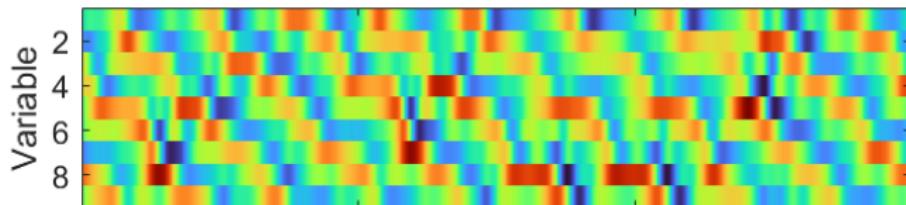
- Resolved variables:  $(x_k)_{k=1}^J = x \in \mathcal{X} \equiv \mathbb{R}^K$ .
- Unresolved variables:  $(y_{j,k})_{j,k=1}^{J,K} = y \in \mathcal{Y} \equiv \mathbb{R}^{JK}$ .
- Flux terms:  $Z : \mathcal{Y} \rightarrow \mathbb{R}^K$ ,  $Z_k(y) = h_x \sum_{j=1}^J y_{j,k} / J$ .
- Chaotic regime:  $K = 9$ ,  $J = 8$ ,  $h_x = -0.8$ ,  $h_y = 1.0$ .

## Lorenz 96 multiscale

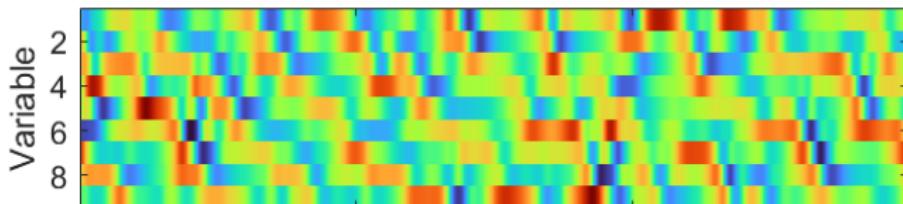
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L96 multiscale



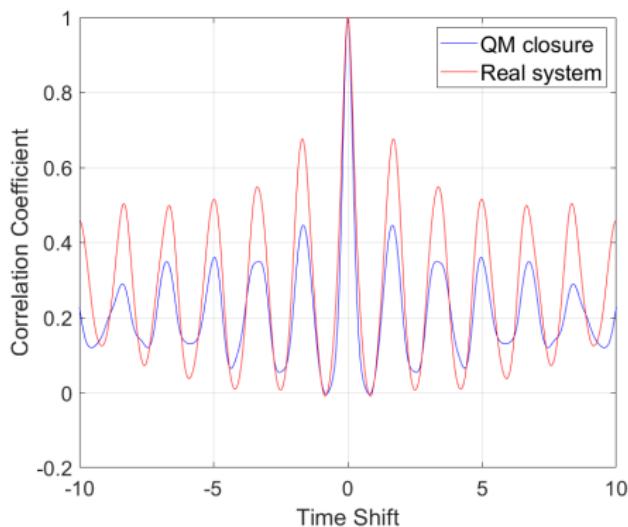
QM closure



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