

**Theorem 1** (Folland Theorem 2.28). *Suppose that  $f$  is a bounded real-valued function on  $[a, b]$ .*

1. *If  $f$  is Riemann integrable, then  $f$  is Lebesgue measurable (and therefore integrable). Furthermore*

$$\mathcal{R} \int_a^b f = \int_{[a,b]} f(x) dm(x). \quad (1)$$

*(Henceforth, we will dispense with the notations in (1) and write simply  $\int_a^b f(x)dx$ .)*

2. *Also,  $f$  is Riemann integrable if and only if the set of discontinuities of  $f$  has measure zero.*

*Proof.* Let  $\mathcal{P} = \{a = t_0 < t_1 < \dots < t_n = b\}$  be a partition of  $[a, b]$  and define

$$l_{\mathcal{P}} := \sum_{i=1}^n m_i \mathbb{I}_{(t_{i-1}, t_i]} \quad \text{and} \quad u_{\mathcal{P}} := \sum_{i=1}^n M_i \mathbb{I}_{(t_{i-1}, t_i]},$$

where

$$m_i := \inf\{f(x) : x \in [t_{i-1}, t_i]\} \quad \text{and} \quad M_i := \sup\{f(x) : x \in [t_{i-1}, t_i]\}.$$

Notice that

$$\int l_{\mathcal{P}} = L(f, \mathcal{P}) \quad \text{and} \quad \int u_{\mathcal{P}} = U(f, \mathcal{P}).$$

We can choose sequences of partitions  $\{\mathcal{Q}_k\}$  and  $\{\mathcal{R}_k\}$  such that

$$\lim_k L(f, \mathcal{Q}_k) = \mathcal{R} \int_a^b f \quad \text{and} \quad \lim_k U(f, \mathcal{R}_k) = \overline{\mathcal{R} \int_a^b f}. \quad (2)$$

Let  $\mathcal{P}_k = \{a = t_0 < \dots < t_n = b\}$  be a partition which is refinement of the partitions  $\mathcal{Q}_k$  and  $\mathcal{R}_k$  as well as  $\mathcal{P}_{k-1}$ , and which also has the property that  $\|\mathcal{P}_k\| := \max(t_i - t_{i-1}) < \frac{1}{k}$ . Since  $\mathcal{P}_k$  is a refinement of both  $\mathcal{Q}_k$  and  $\mathcal{R}_k$ , (2) holds with  $\mathcal{Q}_k$  and  $\mathcal{R}_k$  each replaced by  $\mathcal{P}_k$ . Since  $\mathcal{P}_{k+1}$  is a refinement of  $\mathcal{P}_k$ , it follows that

$$l_{\mathcal{P}_{k+1}} \geq l_{\mathcal{P}_k} \quad \text{and} \quad u_{\mathcal{P}_{k+1}} \leq u_{\mathcal{P}_k}.$$

Therefore we obtain bounded measurable functions  $l$  and  $u$  on  $[a, b]$  by

$$l := \sup_k l_{\mathcal{P}_k} = \lim_k l_{\mathcal{P}_k} \quad \text{and} \quad u := \inf_k u_{\mathcal{P}_k} = \lim_k u_{\mathcal{P}_k}.$$

Clearly

$$l \leq f \leq u.$$

Since bounded functions are Lebesgue integrable on  $[a, b]$  and since  $u = \lim_k u_{\mathcal{P}_k}$  and  $l = \lim_k l_{\mathcal{P}_k}$ , the Lebesgue Dominated Convergence Theorem implies that

$$\int l = \mathcal{R} \int_a^b f \quad \text{and} \quad \int u = \mathcal{R} \int_a^b f.$$

Now if  $f$  is Riemann integrable, the upper and lower integrals coincide and we have

$$\int (u - l) = 0.$$

Since  $u - l \geq 0$ , this implies that  $l = f = u$  a.e. Since Lebesgue measure is complete,  $f$  is measurable, and

$$\mathcal{R} \int_a^b f = \int f.$$

This proves the first part.

To prove the second assertion, first observe that if  $x \in [a, b]$  and if  $0 < \delta < \delta'$ , then

$$\sup\{f(y) : |y - x| \leq \delta\} \leq \sup\{f(y) : |y - x| \leq \delta'\}.$$

It follows that

$$\limsup_{\delta \rightarrow 0} \{f(y) : |y - x| \leq \delta\} = \inf_{\delta > 0} \sup\{f(y) : |y - x| \leq \delta\}. \quad (3)$$

Thus we get a well defined function  $H$  on  $[a, b]$  by setting  $H(x)$  equal to (3). Similarly, we can define  $h$  on  $[a, b]$  by

$$h(x) := \liminf_{\delta \rightarrow 0} \{f(y) : |y - x| \leq \delta\} = \sup_{\delta > 0} \inf\{f(y) : |y - x| \leq \delta\}. \quad (4)$$

We clearly have  $h(x) \leq f(x) \leq H(x)$  for all  $x \in [a, b]$ .

Suppose that  $f$  is continuous at  $x$ . Then given  $\epsilon > 0$  there is a  $\delta > 0$  such that whenever  $|y - x| \leq \delta$  we have  $|f(y) - f(x)| < \epsilon$ . This is the same as

$$f(x) - \epsilon < f(y) < f(x) + \epsilon. \quad (5)$$

It follows from (3) and (5) that  $H(x) < f(x) + \epsilon$ . Since  $\epsilon$  is arbitrary, we must have  $H(x) \leq f(x)$ . Thus  $H(x) = f(x)$  in the event that  $f$  is continuous at  $x$ . Similarly, combining (3) and (4) shows that  $h(x) > f(x) - \epsilon$  for any  $\epsilon > 0$ . Thus forces  $h(x) = f(x)$  when  $f$  is continuous at  $x$ . In particular,  $H(x) = h(x)$  if  $f$  is continuous at  $x$ .

Now suppose that  $H(x) = h(x)$ . Note that the common value must be  $f(x)$ . Thus given  $\epsilon > 0$ , there is — in view of (3) and (4) — a  $\delta > 0$  such that

$$f(x) + \epsilon = H(x) + \epsilon > \sup\{f(y) : |y - x| \leq \delta\} \quad \text{and} \quad (6)$$

$$f(x) - \epsilon = h(x) - \epsilon < \inf\{f(y) : |y - x| \leq \delta\}. \quad (7)$$

Thus if  $|y - x| < \delta$ , then we have

$$f(x) - \epsilon < f(y) < f(x) + \epsilon \quad \text{or} \quad |f(y) - f(x)| < \epsilon.$$

This shows that  $f$  is continuous at  $x$  if and only if  $H(x) = h(x)$ .<sup>1</sup>

If  $\mathcal{P} = \{a = t_0 < \dots < t_n = b\}$  is any partition of  $[a, b]$  and if  $x \notin \mathcal{P}$ , then there is a  $\delta > 0$  such that  $\{y : |y - x| \leq \delta\} \cap \mathcal{P} = \emptyset$ . In particular,  $\{y : |y - x| \leq \delta\} \subset (t_{i-1}, t_i)$  for some  $i$ , and

$$M_i \geq \sup\{f(y) : |y - x| \leq \delta\}.$$

It follows that  $u_{\mathcal{P}}(x) \geq H(x)$  for all  $x \notin \mathcal{P}$ . Now let

$$N := \bigcup_k \mathcal{P}_k.$$

Then  $N$  is countable, and therefore has Lebesgue measure 0. Furthermore if  $x \notin N$ , then

$$u(x) := \inf u_{\mathcal{P}_k}(x) \geq H(x).$$

On the other hand, given  $x \in N$  and  $\epsilon > 0$ , there is a  $\delta > 0$  such that

$$H(x) + \epsilon > \sup\{f(y) : |y - x| \leq \delta\}.$$

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<sup>1</sup>This is the first of Folland's suggested "Lemmas".

Pick  $k$  such that  $\frac{1}{k} < \delta$ . Since  $x \notin \mathcal{P}_k$ ,  $x \in (t_{i-1}, t_i)$  for some subinterval in  $\mathcal{P}_k$ . Since  $\|\mathcal{P}_k\| < \frac{1}{k}$ ,  $M_i \leq \sup\{f(y) : |y - x| \leq \delta\}$  and

$$H(x) + \epsilon > u_{\mathcal{P}_k}(x) \geq u(x).$$

Since  $\epsilon$  was arbitrary, we conclude that  $H(x) = u(x)$  for all  $x \notin N$ . In particular,  $H$  is measurable and

$$\int H = \mathcal{R} \int_a^b f.$$

A similar argument implies that  $h(x) = l(x)$  for all  $x \notin N$ . Thus  $h$  is measurable and<sup>2</sup>

$$\int h = \mathcal{R} \int_a^b f.$$

Now if  $f$  is continuous almost everywhere, it follows that  $H = h$  a.e. Thus the upper and lower Riemann integrals must be equal and  $f$  is Riemann integrable. On the other hand, if  $f$  is Riemann integrable, the upper and lower integrals are equal and

$$\int (H - h) = 0.$$

Since  $H - h \geq 0$ , we must have  $H = h$  a.e. It follows that  $f$  is continuous almost everywhere.  $\square$

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<sup>2</sup>This is essentially Folland's Lemma (b).