

Math 11
Fall 2016
Section 1
Friday, September 16, 2016

First, some important points from the last class:

$$\vec{v} \cdot \vec{w} = |\vec{v}| |\vec{w}| \cos(\theta),$$

where θ is the angle between \vec{v} and \vec{w} .

$$\langle a_1, a_2, a_3 \rangle \cdot \langle b_1, b_2, b_3 \rangle = a_1 b_1 + a_2 b_2 + a_3 b_3$$

The scalar projection of \vec{F} onto \vec{d} is

$$\text{proj}_{\vec{d}}(\vec{F}) = |\vec{F}| \cos(\theta) = \boxed{\frac{\vec{F} \cdot \vec{d}}{|\vec{d}|}}$$

and the vector projection of \vec{F} onto \vec{d} is

$$\overrightarrow{\text{proj}}_{\vec{d}}(\vec{F}) = \left(\frac{|\vec{F}| \cos(\theta)}{|\vec{d}|} \right) \vec{d} = \boxed{\left(\frac{\vec{F} \cdot \vec{d}}{\vec{d} \cdot \vec{d}} \right) \vec{d}}$$

The work done by force \vec{F} on an object moving in a straight line with displacement \vec{d} is

$$\boxed{W = \vec{F} \cdot \vec{d}}$$

“Work equals force dot displacement.”

$$\vec{v} \cdot \vec{w} = \vec{w} \cdot \vec{v}$$

$$\vec{v} \cdot (\vec{w} + \vec{u}) = (\vec{v} \cdot \vec{w}) + (\vec{v} \cdot \vec{u})$$

$$\vec{v} \cdot (\vec{w} - \vec{u}) = (\vec{v} \cdot \vec{w}) - (\vec{v} \cdot \vec{u})$$

$$(t\vec{v}) \cdot \vec{w} = t(\vec{v} \cdot \vec{w}) = \vec{v} \cdot (t\vec{w})$$

$$\vec{0} \cdot \vec{v} = 0$$

$$\vec{v} \cdot \vec{v} = |\vec{v}|^2$$

Definition: The cross product, or vector product, of vectors \vec{r} and \vec{F} is the vector $\vec{r} \times \vec{F}$ with the following properties:

1. $|\vec{r} \times \vec{F}| = |\vec{r}| |\vec{F}| \sin(\theta)$ where θ is the angle between \vec{r} and \vec{F} .
2. $\vec{r} \times \vec{F}$ is perpendicular to both \vec{r} and \vec{F} .
3. \vec{r} , \vec{F} and $\vec{r} \times \vec{F}$ are oriented according to the right-hand rule: If all three vectors are drawn from the same point, and you are looking down from the top of $\vec{r} \times \vec{F}$, rotating from \vec{r} around to \vec{F} appears as a counterclockwise rotation.

$|\vec{r} \times \vec{F}|$ is the area of the parallelogram with edges \vec{r} and \vec{F} .

$$\langle v_1, v_2, v_3 \rangle \times \langle w_1, w_2, w_3 \rangle = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix}$$

Theorem:

$$\begin{aligned} \vec{v} \times \vec{w} &= -(\vec{w} \times \vec{v}) \\ t(\vec{v} \times \vec{w}) &= t\vec{v} \times \vec{w} = \vec{v} \times t\vec{w} \\ \vec{v} \times (\vec{w} + \vec{u}) &= (\vec{v} \times \vec{w}) + (\vec{v} \times \vec{u}) \\ \vec{v} \times (\vec{w} \times \vec{u}) &= (\vec{v} \cdot \vec{u})\vec{w} - (\vec{v} \cdot \vec{w})\vec{u} \end{aligned}$$

Warning: The cross product is *not* associative.

Definition: The *triple product* of $\vec{v} = \langle v_1, v_2, v_3 \rangle$, $\vec{w} = \langle w_1, w_2, w_3 \rangle$, and $\vec{u} = \langle u_1, u_2, u_3 \rangle$, in that order, is

$$\vec{v} \cdot (\vec{w} \times \vec{u}) = (\vec{v} \times \vec{w}) \cdot \vec{u} = \begin{vmatrix} v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \\ u_1 & u_2 & u_3 \end{vmatrix}.$$

Theorem: The absolute value of the triple product of \vec{v} , \vec{w} , and \vec{u} is the volume of the parallelepiped with edges \vec{v} , \vec{w} , and \vec{u} .

The triple product is positive if \vec{v} , \vec{w} , and \vec{u} are oriented according to the right hand rule in the same way as \hat{i} , \hat{j} , and \hat{k} . It is negative otherwise.

Warm-up Questions:

Suppose an object starts at point (a, b, c) and moves with constant velocity $\vec{v} = \langle x_v, y_v, z_v \rangle$ for t seconds.

What is its final position?

Suggestion: Find the following:

A unit vector in the direction of the object's motion: $\frac{1}{|\vec{v}|}\vec{v}$

The object's speed is $|\vec{v}|$, the magnitude of the velocity vector.

The distance the object travels: (time)(speed) = $t|\vec{v}|$

The object's displacement: (distance)(direction vector) = $(t|\vec{v}|)\left(\frac{1}{|\vec{v}|}\vec{v}\right) = t\vec{v}$

(Finally) the object's final position vector:

(initial position vector) + (displacement) = $\langle a, b, c \rangle + t\vec{v} = \langle a + x_v t, b + y_v t, c + z_v t \rangle$

What geometric object does the set of all points of the form $(a + x_v t, b + y_v t, c + z_v t)$ describe? (Be as specific as you can. For example, if the object were a sphere, a complete answer would also identify the center and radius.)

A line through the point (a, b, c) parallel to the vector $\vec{v} = \langle x_v, y_v, z_v \rangle$. Note we can also write

$$\underbrace{\langle x, y, z \rangle}_{\text{general point on line}} = \underbrace{\langle a, b, c \rangle}_{\text{given point on line}} + t \underbrace{\langle x_v, y_v, z_v \rangle}_{\text{vector parallel to line}} .$$

What does the equation

$$\langle 1, 2, -1 \rangle \cdot \langle x, y, z \rangle = 0$$

say about the position vector of the point (x, y, z) ?

It is normal (orthogonal, perpendicular) to the vector $\langle 1, 2, -1 \rangle$.

What geometric object does the equation

$$x + 2y - z = 0$$

describe?

A plane containing the origin and perpendicular to the vector $\langle 1, 2, -1 \rangle$.

Definition: A *vector parametric equation* for the line parallel to vector $\vec{v} = \langle x_v, y_v, z_v \rangle$ passing through the point (x_0, y_0, z_0) with position vector $\vec{r}_0 = \langle x_0, y_0, z_0 \rangle$ is

$$\vec{r} = \vec{r}_0 + t\vec{v}.$$

Here \vec{r} is a variable vector, $\vec{r} = \langle x, y, z \rangle$, so this is

$$\langle x, y, z \rangle = \langle x_0, y_0, z_0 \rangle + t \langle x_v, y_v, z_v \rangle.$$

Scalar parametric equations for this line are

$$x = x_0 + tx_v \quad y = y_0 + ty_v \quad z = z_0 + tz_v.$$

The variable t is a *parameter*. Different values of the parameter give different points on the line.

As another example,

$$x = \cos \theta \quad y = \sin \theta$$

are parametric equations for the unit circle in \mathbb{R}^2 . Different values of the parameter θ give different points on the unit circle.

Example: Find a vector parametric equation for the line through the points $(1, 1, 1)$ and $(2, 3, 4)$.

Point on line: $(1, 1, 1)$

Vector in direction of line: $\langle 2, 3, 4 \rangle - \langle 1, 1, 1 \rangle = \langle 1, 2, 3 \rangle$.

Equation: $\vec{r} = \langle 1, 1, 1 \rangle + t \langle 1, 2, 3 \rangle$.

Example: Find scalar parametric equations for the line through the origin parallel to this line.

Point on line: $(0, 0, 0)$

Vector in direction of line: $\langle 1, 2, 3 \rangle$.

Vector equation: $\vec{r} = \langle 0, 0, 0 \rangle + t \langle 1, 2, 3 \rangle$.

Scalar equations: $x = t \quad y = 2t \quad z = 3t$.

Note: You can also read in the textbook about symmetric equations for a line.

Definition: A *vector equation* for the plane perpendicular to the vector $\vec{n} = \langle a, b, c \rangle$ containing the point (x_0, y_0, z_0) with position vector $\vec{r}_0 = \langle x_0, y_0, z_0 \rangle$ is

$$\vec{n} \cdot (\vec{r} - \vec{r}_0) = 0$$

We can turn this into a scalar equation (a linear equation), sometimes called an implicit equation by WeBWorK, as follows:

$$\langle a, b, c \rangle \cdot (\langle x, y, z \rangle - \langle x_0, y_0, z_0 \rangle) = 0$$

$$\langle a, b, c \rangle \cdot \langle x - x_0, y - y_0, z - z_0 \rangle = 0$$

$$a(x - x_0) + b(y - y_0) + c(z - z_0) = 0$$

$$ax - ax_0 + by - by_0 + cz - cz_0 = 0$$

$$ax + by + cz = ax_0 + by_0 + cz_0$$

Note: From a linear equation $ax + by + cz = d$ for a plane, you can read off the normal vector $\vec{n} = \langle a, b, c \rangle$.

Example: Find an equation for the plane containing the point $(1, 2, 5)$ parallel to the plane with equation

$$x - 2y + z = 5.$$

Vector normal to plane: $\vec{n} = \langle 1, -2, 1 \rangle$.

Point on plane: $(x_0, y_0, z_0) = (1, 2, 5)$.

Linear equation: $x - 2y + z = 1 - 2(2) + 5 = 2$.

Vector equation: $\langle x - 1, y - 2, z - 5 \rangle \cdot \langle 1, -2, 1 \rangle = \langle 0, 0, 0 \rangle$.

Or: $(\vec{r} - \langle 1, 2, 5 \rangle) \cdot \langle 1, -2, 1 \rangle = \vec{0}$.

Example: Find a linear equation for the plane containing the points $(1, 1, 1)$, $(1, 2, 3)$, and $(-1, -1, 1)$.

Vectors parallel to plane: $\langle 1, 2, 3 \rangle - \langle 1, 1, 1 \rangle = \langle 0, 1, 2 \rangle$, $\langle -1, -1, 1 \rangle - \langle 1, 1, 1 \rangle = \langle -2, -2, 0 \rangle$.

Vector normal to plane: $\langle 0, 1, 2 \rangle \times \langle -2, -2, 0 \rangle = \langle 4, -4, 2 \rangle$.

Point on plane: $\langle 1, 1, 1 \rangle$

Equation: $4x - 4y + 2z = 4(1) - 4(1) + 2(1) = 2$, or $\boxed{2x - 2y + z = 1}$.

To check: See whether all 3 points satisfy the equation.

Definition: A vector parametric equation for the plane containing the point with position vector \vec{r}_0 and parallel to both vectors \vec{v} and \vec{w} (which are not parallel to each other) is

$$\vec{r} = \vec{r}_0 + t\vec{v} + s\vec{w}.$$

We will not use vector parametric equations for planes until later in the course, when we talk about surfaces in general. However, understanding vector parametric equations for planes is a good warm-up for that part of the course.

Definition: Planes are called parallel if they have parallel normal vectors. The angle between two planes is the angle between their normal vectors.

Example: Find the distance from the point $(1, 2, 3)$ to the plane with equation

$$x + y + z = 3.$$

Example: Does the line through the points $(7, 9, 3)$ and $(-2, -3, 0)$ intersect the line through the points $(2, 2, 3)$ and $(0, 0, -1)$?

Example: Find the distance between the skew lines (lines that are not parallel but do not meet) $\vec{r} = \langle -1, -2, 1 \rangle + t \langle 1, -1, 0 \rangle$ and $\vec{r} = \langle 1, 0, 1 \rangle + t \langle 1, 1, -1 \rangle$.

To do this, find a vector \vec{n} that is perpendicular to both lines. Then take any points P on the first line and Q on the second line, and take the absolute value of the scalar projection of \overrightarrow{PQ} on the vector \vec{n} .

Explain why this works. (Hint: Think of writing \overrightarrow{PQ} as the sum of three components, one parallel to the first line, one perpendicular to both lines, and one parallel to the second line. Draw a picture, with these vectors position head-to-tail making a path starting at P and ending at Q . Explain why the length of the second leg of the path is the distance between the lines.)

Do not try to memorize the various formulas for the distances between a point and a line, between a point and a plane, between two lines, between a line and a plane, between two planes.

Example: Find a linear equation for the plane through the origin that is parallel to both the lines $\vec{r} = \langle -1, -2, 1 \rangle + t \langle 1, -1, 0 \rangle$ and $\vec{r} = \langle 1, 0, 1 \rangle + t \langle 1, 1, -1 \rangle$.

Example: Find the distance between the parallel planes

$$x + 2y - z = 20$$

$$2x + 4y - 2z = 20.$$