Winter 2020 Math 106 Topics in Applied Mathematics Data-driven Uncertainty Quantification

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# Lecture 11: Smoothing using Orthogonal Functions

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Let  $X_1, X_2, ..., X_n$  be IID observations from a distribution on [0, 1] with density f. If we assume that  $f \in L^2$ , we can write

$$f(x) = \sum_{j=0}^{\infty} \beta_j \phi_j(x)$$

where  $\{\phi_j\}$  is an orthonormal basis of  $L^2[0,1]$ .

• If we know f(x), the coefficient  $\beta_j$  is given by

$$\beta_j = \int_{[0,1]} f(x)\phi_j(x)dx.$$

- The above formula looks similar to the Kernel density estimation. But the basis function \(\phi\_j(x)\) does not necessarily have measure 1 in contrast to the Kernel.
- Without knowing f(x), how can we calculate the coefficient  $\beta_j$ ? We need to estimate it using the data.

• The estimate 
$$\hat{\beta}_j$$
 of  $\beta_j$  is given by

$$\hat{\beta}_j = \frac{1}{n} \sum_{i}^{n} \phi_j(x_i)$$

**Theorem.** The mean and variance of  $\hat{\beta}_i$  are

$$E[\hat{\beta}_j] = \beta_j, \quad Var(\hat{\beta}_j) = \frac{\sigma_j^2}{n}$$

where  $\sigma_j^2 = Var(\phi_j(X_i)) = \int (\phi_j(x) - \beta_j)^2 f(x) dx$ . **Proof.** 

$$E[\hat{\beta}_j] = \frac{1}{n} \sum_{i}^{n} E[\phi_j(X_i)] = E[\phi_j(X_1)] = \int \phi_j(x) f(x) dx = \beta_j.$$

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$$\mathsf{E}[\hat{\beta}_j] = \frac{1}{n} \sum_{i}^{n} \mathsf{E}[\phi_j(X_i)] = \mathsf{E}[\phi_j(X_1)] = \int \phi_j(x) f(x) dx = \beta_j.$$

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**Exercise.** Prove the variance.

For a given f(x), we know that

$$\sum_{j}^{J} \beta_{j} \phi_{j}(x) \tag{1}$$

is more accurate if  $J \in \mathbb{N}$  increases.

- This is not true anymore with the estimates {β<sub>j</sub>}. Think about the regression. A higher order polynomial regression function is not always better than a lower order polynomial regression function (bias and variance tradeoff).
- J is called the smoothing parameter. It is typically chosen between 1 and √n where n is the sample size. J is chosen so that it minimizes the risk (or mean integrated squared error).

## 11.1 Density estimation using orthogonal functions Let $\hat{f}(x)$ is an estimate of f(x) given by

$$\hat{f}(x) = \sum_{j}^{J} \hat{eta}_{j} \phi_{j}(x).$$

Remember that the risk of  $\hat{f}$  using a smoothing parameter J is the expected value of the  $L^2$  error, that is

$$R(J) = E\left[\int (\hat{f}(x) - f(x))^2 dx\right] = \sum_{j=1}^{J} \frac{\sigma_j^2}{n} + \sum_{j=J+1}^{\infty} \beta_j^2.$$

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**Theorem.** An estimate of the risk R(J) is

$$\hat{R}(J) = \sum_{j=1}^{J} \frac{\hat{\sigma}_j^2}{n} + \sum_{j=J+1}^{\infty} \left( \hat{\beta}_j^2 - \frac{\hat{\sigma}_j^2}{n} \right)_+$$

where  $a_+ = \max\{a, 0\}$  and

$$\hat{a}_j^2 = rac{1}{n-1}\sum_i^n \left(\phi_j(X_i) - \hat{\beta}_j\right)^2.$$

• Using the  $J^*$  that minimizes  $\hat{R}(J)$ , the estimate of the density  $\hat{f}(x)$  is given by

$$\hat{f}(x) = \sum_{j}^{J^*} \hat{\beta}_j \phi_j(x)$$

Note that f̂(x) can be negative!! If so, take f̂\* = max(f̂, 0) and normalize it.

#### 11.2 Regression

For a data set  $\{X_i, Y_i\}$ ,

Remember that the regression function r(x) is defined as the expected value of Y given x

$$r(x) = E[Y|X = x].$$

- We studied parametric and nonparametric regressions. In particular, for nonparametric regression, we know a kernel density estimation based regression method.
- It is also possible to calculate a regression function using density estimation with orthogonal functions.
- Assume that r(x) is in  $L^2(0,1)$  and  $x_i$  is uniformly distributed.
- $r(x) = \sum_{j=1}^{\infty} \beta_j \phi_j(x)$  where  $\beta_j = \int_0^1 r(x) \phi_j(x) dx$  for an orthonormal basis  $\{\phi_j\}$  of  $L^2(0, 1)$ .

## 11.2 Regression

• The estimate of 
$$eta_j$$
,  $\hateta_j$  is given by

$$\hat{\beta}_j = \frac{1}{n} \sum_{i=1}^n Y_i \phi_j(x_i), \quad j = 1, 2, \dots$$

Theorem.

$$\hat{\beta}_j \sim N(\beta_j, \frac{\sigma^2}{n})$$

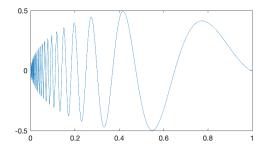
where  $\sigma^2$  is the variance of the measurement error  $e_i$ 

$$Y_i = r(x_i) + e_i$$

Idea of Proof. For the mean,

$$E[\hat{\beta}_j] = \frac{1}{n} \sum_{i=1}^n E[Y_i] \phi_j(x_i) = \frac{1}{n} \sum_{i=1}^n r(x_i) \phi_j(x_i)$$
$$\sim \int r(x) \phi_j(x) dx = \beta_j.$$

- Suppose that a regression function r(x) has a sharp jump but that r(x) is otherwise very smooth. That is, r(x) is spatially inhomogeneous.
- Doppler function  $\sqrt{x(1-x)}\sin\left(\frac{2.1\pi}{x+.05}\right)$



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Wavelets are local orthogonal functions. Harr wavelet.

Harr father wavelet (or Harr scaling function)

$$\phi(x) = \begin{cases} 1 & \text{if } 0 \le x < 1 \\ 0 & otherwise. \end{cases}$$

Haar mother wavelet

$$\psi(x) = \begin{cases} -1 & \text{if } 0 \le x \le 1/2 \\ 1 & \text{if } 1/2 < x \le 1 \end{cases}$$

For any integers j and k define

$$\psi_{j,k}(x) = 2^{j/2}\psi(2^{j}x-k).$$

▶ Let W<sub>j</sub> = {ψ<sub>jk</sub>, k = 1, 2, ..., 2<sup>j</sup> − 1} be the set of rescaled and shifted mother wavelets at resolution j.

#### Theorem. The set of functions

 $\{\phi, W_0, W_1, \ldots\}$ 

is an orthonormal basis for  $L^2(0,1)$ . Corollary. For any  $f \in L^2(0,1)$ ,

$$f(x) = \alpha \phi(x) + \sum_{j=1}^{\infty} \sum_{k=0}^{2^{j}-1} \beta_{j,k} \psi_{j,k}(x)$$

where  $\alpha = \int_0^1 f(x)\phi(x)dx$ ,  $\beta_{j,k} = \int_0^1 f(x)\psi_{j,k}(x)dx$ .

- $\alpha$  is called scaling coefficient.
- $\beta_{j,k}$  are called **detail coefficients**.
- ▶ In a finite sum approximation of *f* using *J* different scales

$$f(x) = \alpha \phi(x) + \sum_{j}^{J} \sum_{k=0}^{2^{j}-1} \beta_{j,k} \psi_{j,k}(x)$$

J represents the resolution of the approximation.

#### Regression.

- Consider the regression model  $Y_i = r(x_i) + \sigma e_i$  where  $e \sim N(0, 1)$  and  $x_i = i/n$ .
- For simplicity, assume that  $n = 2^J$  for some J.
- Smoothing with wavelets requires thresholding instead of truncation. That is, instead of choosing a smoothing parameter that determines the number of terms to keep, thresholding keeps coefficients that are sufficiently large.
- One example of thresholding is hard, universal thresholding.

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#### Hard, universal thresholding.

1. Calculate

$$\hat{\alpha} = \frac{1}{n} \sum_{i} \phi_k(x_i) Y_i$$
, and  $D_{j,k} = \frac{1}{n} \sum_{k} \psi_{j,k}(x_i) Y_i$ 

for  $0 \leq j \leq J - 1$  where  $J = \log_2(n)$ .

2. Apply universal thresholding

 $\hat{\beta}_{j,k} = \left\{ \begin{array}{ll} D_{j,k} & \text{if } |D_{j,k}| > \text{threshold value} \\ 0 & \text{otherwise} \end{array} \right.$ 

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3. Set  $\hat{r}(x) = \hat{\alpha}\phi(x) + \sum_{j=0}^{J-1} \sum_{k=0}^{2^j-1} \hat{b}_{j,k}\psi_{j,k}(x)$ .

#### Homework

For n = 10,000, set  $x_i = i/n$  and  $y_i = doppler(x_i) + e_i$  where  $e_i \sim N(0,0.05^2)$ .

- 1. Use the trigonometric functions to estimate the regression function.
- 2. Use the Legendre polynomials to estimate the regression function.
- 3. Use the Harr wavelets to estimate the regression function.

For 1-3, try to use a small number of terms. You are okay to use any programming libraries (that is, you do not need to make your own code; just use standard libraries) but specify all parameters to get your estimates.

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