

Barnett
7/31/17

Your name: _____

SOLUTIONS

Math 22 Summer 2017, mini-quiz 2, Mon July 31

10 pts total

Please show your work. No credit is given for solutions without work or justification.

[3/15] (1) Compute the determinant of $A = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 2 & 0 & 5 & 6 \\ 3 & 0 & 1 & 1 \\ 4 & 2 & 1 & 1 \end{bmatrix}$.

cofactor expansion about col 2.
signs $-, +, -, +$

$$\begin{aligned} \det A &= \oplus 2 \begin{vmatrix} 1 & 1 & 0 \\ 2 & 5 & 6 \\ 3 & 1 & 1 \end{vmatrix} \leftarrow \text{expand 1st row (since has a zero)} \\ &= 2 \left(1 \begin{vmatrix} 5 & 6 \\ 1 & 1 \end{vmatrix} - 1 \begin{vmatrix} 2 & 6 \\ 3 & 1 \end{vmatrix} \right) \\ &= 2 \left(5(1) - 6(1) - (2(1) - 6(3)) \right) \\ &= 2(15) = 30. \end{aligned}$$

Note merely stating rows of A (or cols) are a basis, without proof, is inadequate.

another version: $\det A \neq 0$ so by IMT, rows of A are L.I. since cols of A^T are, since A^T invertible. Since rows of A span Row A , they are a basis.

[2/15]

(2) Use the result from question 1 to find a basis for Row A , where A is the matrix from question 1, without row reducing:

$\det A \neq 0$, so A is invertible, so A has full rank (all pivots, i.e. 4 of them), by IMT.

Thus Row A has dimension 4, so is equal to \mathbb{R}^4 .

A basis is thus $\{\vec{e}_1, \vec{e}_2, \vec{e}_3, \vec{e}_4\}$, the standard basis for \mathbb{R}^4 .

Alternatively, A row equivalent to I_4 , so rows of I_4 (or columns) are a basis for Row A .

It's also true that the rows (or cols) of A are a basis for Row A .

(3) Let $H = \left\{ \begin{bmatrix} a \\ b \\ c \end{bmatrix} : 2a + b - c = 0 \right\}$. \leftarrow Here a, b, c are real numbers.

[2pts] (a) Prove H is a vector space. [Hint: there is no time nor space to test the basic axioms] \uparrow call.

$$H = \text{Nul } A, \text{ for } A = [2 \ 1 \ -1], \text{ a } 1 \times 3 \text{ matrix.}$$

From class, any nullspace is a subspace, here of \mathbb{R}^3 , hence is also a vector space.

[2pts] (b) Find a basis for H and state $\dim H$.

$$A \sim \begin{bmatrix} 1 & 1/2 & -1/2 \\ 0 & 0 & 0 \end{bmatrix} \quad \begin{matrix} x_2 \text{ free} \\ x_3 \text{ free} \end{matrix}$$

$$\text{so } \vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -1/2 x_2 + 1/2 x_3 \\ x_2 \\ x_3 \end{bmatrix}$$

$$\text{basis is } \left\{ \begin{bmatrix} -1/2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1/2 \\ 0 \\ 1 \end{bmatrix} \right\}, \quad \dim H = 2.$$

[1pt] (c) Every point in H is in the span of the set $\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3$ (the unit vectors in \mathbb{R}^3). Is this set a basis for H , and why?

\uparrow
since already recently tested

No: i) the set is linearly independent, but
ii) $\text{Span}\{\vec{e}_1, \vec{e}_2, \vec{e}_3\} = \mathbb{R}^3 \neq H$.

The span is larger than H , not equal to H as a set.

A good way to prove the latter is by example:

$$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \text{ is in } \text{Span}\{\vec{e}_1, \vec{e}_2, \vec{e}_3\} \text{ but not in } H, \text{ since } 2(1) + 0 - 0 \neq 0.$$