



Lecture 14

Math 22 Summer 2017
July 19, 2017



- ▶ §4.3 Bases of a vector space
- ▶ Midterm1 tonight 6pm - 8pm in Kemeny 008

§4.3 Definition of basis



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A concise way to think about a basis is as a *minimal spanning set*.

§4.3 Examples of bases



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- ▶ $\mathcal{B} = \{1, t, t^2, \dots, t^n\}$ is a basis of \mathbb{P}_n .
- ▶ Let $\mathcal{B} = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ be a set of 3 vectors in \mathbb{R}^3 .

§4.3 Examples of bases



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- ▶ $\mathcal{B} = \{1, t, t^2, \dots, t^n\}$ is a basis of \mathbb{P}_n .
- ▶ Let $\mathcal{B} = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ be a set of 3 vectors in \mathbb{R}^3 .
How can we check if \mathcal{B} is a basis?

§4.3 Theorem 5



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Suppose we have a spanning set and we want to get a basis.

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*Let $S = \{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ be a set of vectors in a vector space V .
Let $H = \text{Span}\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$.*

§4.3 Theorem 5



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*Let $S = \{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ be a set of vectors in a vector space V .
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Let $H = \text{Span}\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$. Then:

1. If one of the vectors (call it \mathbf{v}_k) of S is a linear combination of the rest, then the span of the vectors in S without including \mathbf{v}_k still spans H .



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2. If $H \neq \{\mathbf{0}\}$, then some subset of S is a basis for H .

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What's the proof?

§4.3 Example



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Consider the matrix

$$A = \begin{bmatrix} 1 & 0 & 3 & 0 & 11 & 0 & 0 \\ 0 & 1 & 2 & 0 & 7 & 0 & 0 \\ 0 & 0 & 0 & 1 & 5 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 13 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} .$$

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What changes if A is not in RREF?

§4.3 Example continued



§4.3 Example continued



Now consider the matrix B whose RREF is A .

$$B = \begin{bmatrix} 1 & 0 & 3 & 0 & 11 & 0 & 0 \\ 0 & 1 & 2 & 0 & 7 & -3 & -39 \\ -1 & 0 & -3 & 0 & -11 & 1 & 13 \\ 0 & -2 & -4 & 0 & -14 & 6 & 78 \\ 0 & 0 & 0 & 1 & 5 & 0 & 0 \end{bmatrix}, \quad A = \begin{bmatrix} 1 & 0 & 3 & 0 & 11 & 0 & 0 \\ 0 & 1 & 2 & 0 & 7 & 0 & 0 \\ 0 & 0 & 0 & 1 & 5 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 13 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}.$$

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Let's organize these observations in a theorem...

§4.3 Theorem 6



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§4.3 Classwork

How about some T/F review for the midterm?



§4.3 Classwork



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- ▶ A linear transformation $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is onto if for each $\mathbf{x} \in \mathbb{R}^n$, there is a $\mathbf{b} \in \mathbb{R}^m$ such that $T(\mathbf{x}) = \mathbf{b}$.

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- ▶ If $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4\}$ is a linearly dependent set, then $\mathbf{v}_4 \in \text{Span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$.

§4.3 Classwork



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- ▶ A linear transformation $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is onto if for each $\mathbf{x} \in \mathbb{R}^n$, there is a $\mathbf{b} \in \mathbb{R}^m$ such that $T(\mathbf{x}) = \mathbf{b}$. **False**
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