# Math 56 Compu & Expt Math, Spring 2013: Topics Weeks 1-3 (Midterm 1)

#### 1 Week 1

Relative error

Big O, little o. Know definitions, be able to test if one func is O or o of another, as some parameter goes large or small.

Algebraic convergence, order. Know how to bound tail of algebraic series by integral.

Exponential convergence, rate. How to bound tail by pulling out a geometric series. Thm that rate is asymptotically (dist from center to eval pt)/(dist from center to singularity)

How to choose good axes for a plot so data spread and linear, interpret slope.

Definition of superexponential convergence.

Basic complex arithmetic, magnitude-phase notation.

### 2 Week 2

Taylor's theorem with correct remainder term, using it to bound err. eg using to prove super-exp conv for exp(x)

Newton's iteration. Definition of quadratic convergence (ie  $\varepsilon_{n+1}/\varepsilon_n^2 \leq C$ ), sketch of proof that Newton's is quad conv. Newton's for computing sqrt. Bisection alg from HW.

Set of floating point numbers, their gaps, error due to rounding ie  $f\ell(x)$ . Defn of  $\varepsilon_{\text{mach}}$ . Rules of floating point arithmetic (rounding combined with  $+ - \times /$ )

Summation: sum in order small magnitude to large, and why.

Catastrophic cancellation, spotting it, and using math to rewrite the formula to avoid it.

Relative condition number of a problem  $\kappa(x)$ , defn, how to compute.

Finite differencing to approximate derivatives. One-sided, centered, and 3-pt stencil. How to get their orders and estimating CC error associated with finite-precision evaluation of the function. Derive the approximate optimal choice of h by equating the two sources of error.

#### 3 Week 3

Backwards stability: definition, concept, how to test for it applying rules of floating point to simple functions f(x) or  $f(x_1, x_2)$ , ie one or two inputs.

Bkw Stab Thm: a bkw stab algorithm's relative err bounded by  $\kappa(x)O(\varepsilon_{\text{mach}})$ , apply it.

Stability: definition. (Advanced: be able to test an algorithm for stability.)

Roots of unity in complex plane, eg solving  $z^n = c$  for *n* integer, c > 0 real.

2-norm of a vector, and (induced) norm of a matrix ||A||, definition, understanding in terms of largest growth factor (longest semi-axis of ellipsoid produced when A acts on unit sphere). Formula from HW3:  $||A|| = \sqrt{\lambda_{\max}(A^T A)}$ .

Condition number of a matrix  $\kappa(A) = ||A|| \cdot ||A^{-1}||$ , and that it is *worst-case* bound of  $\kappa$  for the linear system  $A\mathbf{x} = \mathbf{b}$ , with respect to input data  $\mathbf{b}$ .<sup>1</sup>

#### 4 Practise questions

Also see worksheets, homeworks, and Quiz 1. More to follow.

- 1. Prove if  $\log x = O(x)$  as  $x \to \infty$ ? As  $x \to 0$ ?
- 2. The matrix A turns the vector (3, 4) into the vector (5, 12). Use this to give a bound on ||A|| (upper, lower?) Also use it to give a bound on  $||A^{-1}||$  (upper, lower?)
- 3. Use Taylor's theorem to bound the error of the 3-point stencil finite difference approximation to f''(x) with spacing h, in exact arithmetic. State the convergence type and order/rate. If relative errors in evaluating f are  $O(\varepsilon_{\text{mach}})$  what is an optimal choice for h? (Ignore constants size O(1).)
- 4. Compute the norm of matrix  $A = \begin{bmatrix} 1.001 & 1 \\ 1 & 1 \end{bmatrix}$ . How many digits of accuracy do you expect in worst-case for linear system involving A? (An exact computation of  $\kappa$  is messy; feel free to make approximations).
- 5. Bindel–Goodman Ex. 4.6.8.
- 6. From X-hr: a) Prove if  $2N^3 + N^2 = O(N^2)$  as  $N \to \infty$  b) Prove if  $\sin x \log x = o(x)$  as  $x \to \infty$  c) Prove if  $10 \sin x = O(x)$  as  $x \to 0$  d) Prove if  $10 \tan x = O(x)$  as  $x \to 0$ .
- 7. Write a Newton iteration to solve  $x^3 x = 1$ . What function of the error creates a linear graph when plotted vs iteration number n?
- 8. Fixing any x > 0 and r > 0, show that the Taylor series for  $e^x$  about 0 has error  $O(r^n)$ . State the type of convergence this implies.
- 9. Estimate the relative error introduced when a floating point machine evaluates f(x) = 1 + x.
- 10. What is a rigorous bound on the error of the unsymmetric finite-difference approx  $f'(x) \approx \frac{f(x+2h)-f(x-h)}{3h}$ ? Use exact arithmetic (ignore rounding error). Your bound should hold for all h > 0 and may involve properties of f. Then write it in big-O notation.
- 11. Now accounting for floating point error (assume f evaluated to  $\varepsilon_{\text{mach}}$ ), what is the optimal h to get the best accuracy in the previous question? What roughly is this accuracy?

<sup>&</sup>lt;sup>1</sup> for that matter, A too, but we didn't do that

12. Write all solutions to  $z^3 = 8i$  in the form  $re^{i\theta}$ .

## 5 Some practise question answers

- 1. l'Hôpital's rule both times. Ans: Yes, no.
- 2.  $||A|| \ge 13/5$ .  $||A^{-1}|| \ge 5/13$ .
- 3. abs err upper bnd  $(h^2/12) \cdot \max_{q \in (x-h,x+h)} |f'''(q)| = O(h^2)$  ie 2nd-order algebraic convergence. Evaluation error causes  $O(\varepsilon_{\text{mach}}/h^2)$  error in answer. Balancing this against  $O(h^2)$  gives  $h = \varepsilon_{\text{mach}}^{1/2}$ .
- 4. norm is about  $\sqrt{2}$  (I didn't do exactly).  $\kappa(A)$  is about 10<sup>3</sup>, so roughly expect 13 digits in solution.

5.

- 6. they all are.
- 7.  $x_{n+1} = x_n \frac{x_n^3 x_n 1}{3x_n^2 1}$ . Quadratic convergence, so  $\log(\log 1/\varepsilon_n)$  vs *n* linear.
- 8. Taylor theorem, then  $\lim_{n\to\infty} (x/r)^n/n! = 0$ , so is bounded by a const for all sufficiently large n. Super-exponential convergence.
- 9.  $\frac{2|x|+1}{x+1}\varepsilon_{\mathrm{mach}}$
- 10. absolute error is O(h).
- 11.  $h = O(\varepsilon_{\text{mach}}^{1/2}), 8$  digits.
- 12. geom gives  $2e^{i\theta}$  where  $\theta = \pi/6, 5\pi/6, 9\pi/6$  since each angle when tripled gives  $\pi/2$