Math 56 Compu & Expt Math, Spring 2014: Homework 3

due 10am Thursday April 17th

- 1. Here you learn how to "roll your own" finite difference formulae. Let's say you have access to f at only x, x + h, and x + 2h, and want a 2nd-order accurate approximation for f'(x). Note that this is at the leftmost point of the three; e.g. at the extreme end of a grid of values.
 - (a) We want f'(x) ≈ af(x) + bf(x + h) + cf(x + 2h). Our goal is to solve for the coefficients a, b, c, by setting up a 3-by-3 linear system for them, as follows. Expand the right-hand side via Taylor series about x (you don't need the rigorous remainder term). Since you want this to hold for all functions, you may extract the coefficients in front of f(x) to give one equation, the coefficients of f'(x) to give another, and f''(x) for the third.
 - (b) Solve the system either by hand or computer, hence write your new finite difference formula. How do you know the solution is unique?
 - (c) Give a *rigorous* upper bound on the error of this formula (in exact arithmetic, i.e. ignore rounding).
- 2. Stability.
 - (a) Show whether subtraction $x_1 x_2$ is backwards stable (with respect to the two input data) under the rules of floating point.
 - (b) Cosine, like anything else done by machine, cannot be more accurate than a relative error of $\varepsilon_{\text{mach}}$ in its output (ie "forward error"). Explain if a machine implementation of cos could be backwards stable near x = 0? Near $\pi/2$?
- 3. Here's a new formula for matrix 2-norm:

$$||A|| = \sqrt{\lambda_{\max}(A^T A)},$$
 where $\lambda_{\max}(A^T A)$ is the largest eigenvalue of the matrix $A^T A$.

- (a) Let $A = \begin{bmatrix} 1 & -1 \\ 2 & 2 \end{bmatrix}$. Use the new formula to compute by hand ||A||. How does it compare to the size of the largest eigenvalue of A? (for which you can use **eig**)
- (b) Use this to compute the matrix condition number $\kappa(A)$. Is it well-conditioned?
- (c) Take 100 points $\mathbf{x} \in \mathbb{R}^2$ equi-spaced on the unit circle, and plot them, and $A\mathbf{x}$ for each. What geometric property does $\kappa(A)$ measure of the ellipse produced?
- 4. Download the two 100×100 matrices A1 and A2 from the HW page, and use textread to read them into Matlab (you will need to reshape them).
 - (a) Compare their matrix 2-norms and condition numbers. What worst-case relative errors do you expect for solving linear systems with matrix A1? With A2? (Use our backward stability theorem, and assume standard double precision.)
 - (b) Let's focus on A = A1, and load in the RHS $\mathbf{b} = \mathbf{bvec}$ from the HW page. Solve $A\mathbf{x} = \mathbf{b}$. Then perturb \mathbf{b} by a random vector of norm ε_{mach} to get $\tilde{\mathbf{b}}$ (this emulates rounding error applied to the RHS), and solve again $A\tilde{\mathbf{x}} = \tilde{\mathbf{b}}$. What relative norm change $\|\tilde{\mathbf{x}} \mathbf{x}\| / \|\mathbf{x}\|$ results? Does this match your prediction from (a)?
 - (c) Repeat (b) except using the RHS $\mathbf{c} = \mathbf{cvec}$ from the HW page. Surprising? Is it consistent with (a)? Repeat for random unit-norm RHS vectors—do they behave more like \mathbf{b} or like \mathbf{c} ?

- BONUS Explain the different behaviors [hint: $\|\mathbf{x}\|$], deducing how the directions of **b** and **c** relate to long and short axes of the ellipse of the image of the unit sphere under A.
 - (d) Given $A \in \mathbb{R}^{M \times P}$ and $B \in \mathbb{R}^{P \times N}$, prove a bound on ||AB|| in terms of the norms of the individual matrices. [Hint: HW2 6(c).]
- 5. (a) [Trefethen and Bau, Ex. 13.3] On the same axis, plot $p(x) = (x-2)^9$ around its root two ways. First plot it by evaluating p(x) via its factored form, then plot it via its expanded form $p(x) = x^9 18x^8 + 144x^7 672x^6 + 2016x^5 4032x^4 + 5376x^3 4608x^2 + 2304x 512$. Evaluate it at the points x = 1.920, 1.921, 1.922, ..., 2.08. Explain the discrepancy.
 - (b) Compute the roots of $q(x) = x^2 \frac{10000001}{10000}x + 1$ using the quadratic formula (in Matlab). Notice that $q(x) = (x 10000)(x \frac{1}{10000})$. What is the relative error of the computed roots? Explain why one root is good to only 9 digits of accuracy. Can you find a way to get this root to close to machine accuracy using only the input coefficients a, b and c and the other root?