

Matroids are structures that generalize vector spaces, in the way that they are (finite) sets with a notion of independence.

### Definition

A (finite) matroid is a pair  $(S, \mathcal{J})$ , where  $S$  is a finite set and  $\mathcal{J}$  is a collection of subsets of  $S$ , satisfying:

- (i)  $\mathcal{J}$  is nonempty, and if  $J \in \mathcal{J}$  and  $I \subseteq J$ , then  $I \in \mathcal{J}$   
(order ideal property, or simplicial complex property)
- (ii) If  $I, J \in \mathcal{J}$  and  $|I| < |J|$ , there exists  $x \in J \setminus I$  such that  $I \cup \{x\} \in \mathcal{J}$ .

The elements of  $\mathcal{J}$  are the independent sets.

### Examples

- Vector spaces

$S$  = a set of vectors (might not all be linearly independent).

$\mathcal{J}$  = subsets of  $S$  containing linearly independent vectors

- Hyperplane arrangements

Taking  $S$  as the vectors normal to the hyperplanes, and their span is a vector space.

Moreover, if the arrangement is central, the poset we get by inclusion is isomorphic to the intersection lattice.\*

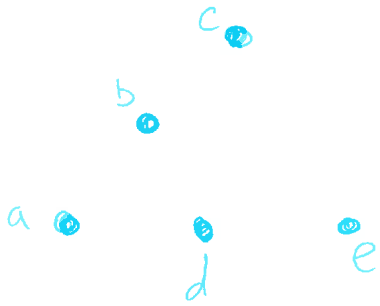
It does not mean that the same is true for the independent sets

\* It might not be obvious

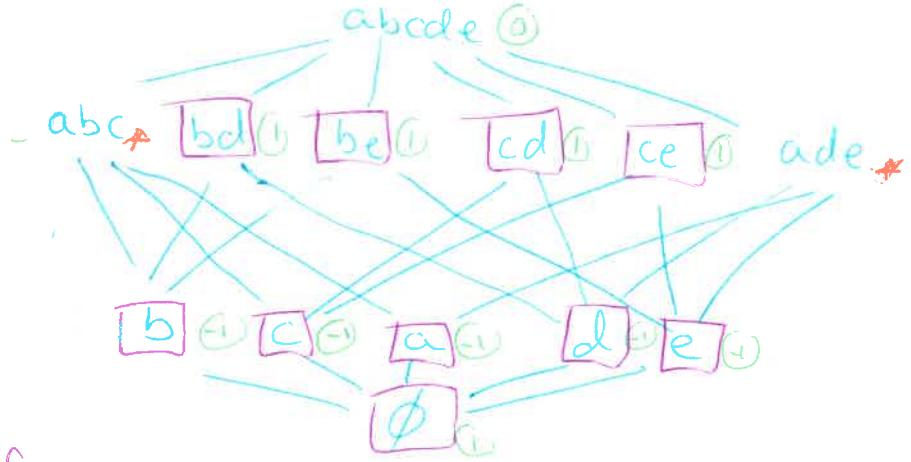
# Example

Let  $a, b, c, d, e$  be points in  $\mathbb{R}^2$  and consider  $\{x, y\}$  to be the minimal affine subspace containing  $x$  and  $y$  (if the set has two elements, it will always be a line, but  $\{x, y, z\}$  could either be a line or a plane).

$$S = \left\{ \{a, b, c, d, e\} \cap W \mid \begin{array}{l} W \text{ is an affine} \\ \text{subspace of } \mathbb{R}^2 \end{array} \right\}$$



The poset  $S$ , ordered by inclusion



$\square$  are the independent sets

for example,  $abc \notin S$

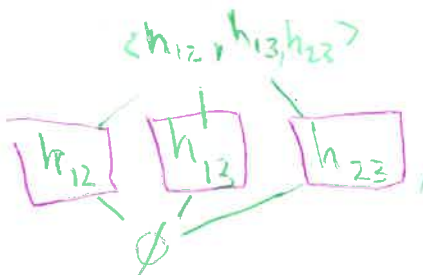
because removing one independent set smaller than  $abc$  returns either  $ab, bc$  or  $ac$ , and none of them are in  $S$ .

Characterization of independence (for this poset):

$A \subseteq \{a, b, c, d, e\}$  is independent iff its rank in the poset is its cardinality.

# Example

$B_3$  as a hyperplane arrangement



where  $h_{ij}$  is normal to  $H_{ij}$ .

# Definitions

- A basis is a maximal independent set
- A circuit is a minimal dependent set.
- The rank of  $A \subseteq S$  is  $\max\{|X| : X \subseteq A, X \in \mathcal{I}\}$ .

## Example

- For vector spaces, a basis is the usual thing we know.
- For a vector space, the rank is the dimension of the space it spans.

## Example

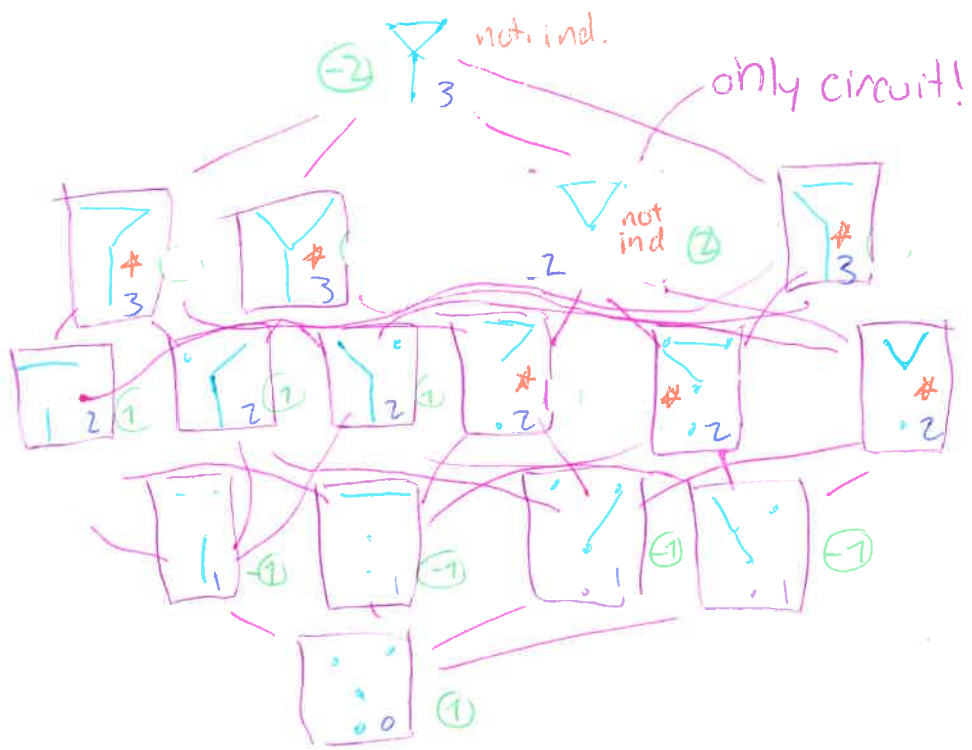
Matroids from a graph  $G = (V, E) =$  

$E$  is the set of elements. A subset of edges is independent if they do not contain a cycle (or, if they are a forest).

$$F = \{B \subseteq E \mid B \text{ is a forest}\}$$

$(E, F)$  is a matroid.

$r$   
rank  
 $\mathcal{I}$  (for a subset)  
\* not closed



### Definition

Fix a total ordering  $\triangleleft$  on  $S$ .

A broken circuit is a subset of  $S$  of the form  $\hat{C} = C \setminus \{\min_{\triangleleft}(C)\}$ , where  $C$  is a circuit

### Example

For the graph on page 3, fix the following order



There is only one circuit in  $\mathbb{Z}^E$ :  $C = \nabla$ , and its minimal element is  $\bar{c}$ . Thus, the only broken circuit of  $(E, F)$  is  $\nabla$ .

### Example

Fix  $a \triangleleft b \triangleleft c \triangleleft d \triangleleft e$ .  $S$  (on page 2) contains circuits  $abc$  and  $dde$ . The 2 broken circuits of  $S$  are  $bc$  and  $de$

The broken circuit complex  $BC(M)$  is an abstract simplicial complex ( $\therefore e, T \in BC(M)$  and  $U \subseteq T \Rightarrow U \in BC(M)$ ) defined by:

$$BC(M) = \{T \subseteq S : T \text{ contains no broken circuit}\}$$

### Example

The broken circuit complex of  $(E, F)$  is all the subsets of  $E$  that do not contain  $\nabla$ . As a simplicial complex, it is spanned by  $\nabla$  and  $\bar{\nabla}$  (i.e. all elements of  $BC$  are included in these two) and we get the following simplicial complex.



Dimension	# faces
-1	1
0	4
1	5
2	2

Example

For the affine spaces on page 2, the broken circuits are  $bc$  and  $de$ . And all elements of  $S$  that do not contain  $bc$  nor  $de$  are included in either  $abd, abe, acd$  or  $ace$ .

Thus, the simplicial complex  $BC(S)$  is



since  $ab, ac, ad, abd, abe, acd$  and  $ace$  are not in  $S$ .

Definition

The closure of a subset  $A$  of  $S$  for a matroid  $(S, \mathcal{I})$  is

$$\text{clos}(A) = \{x \in S \mid \text{rank}(A \cup \{x\}) = \text{rank}(A)\}.$$

A subset  $A$  is closed if  $\text{clos}(A) = A$ .

Alternatively,  $A$  is closed if it is maximal among elements of the same rank.

Definition / Theorem

The characteristic polynomial of a matroid  $M = (S, \mathcal{I})$  admits the

equivalent definitions

$$\bullet \chi_M(t) = \sum_{x \in \text{Clos}(M)} \mu(\hat{0}, x) t^{\text{rank}(M) - \text{rank}(x)},$$

where  $\text{Clos}$  is the induced subposet of closed subsets of  $S$ , and the Möbius function is computed on that poset.

$$\bullet \chi_M(t) = \sum_{i=0}^{\text{rank}(M)} (-1)^i f_{i-1}(BC(M)) t^{\text{rank}(M) - i},$$

where  $f_{i-1}$  is the number of faces of dimension  $i$  in  $BC(M)$ .

Examples

We can compute in two ways the characteristic polynomials of  $S$  and  $(E, F)$ .

$$\chi_S(t) = t^2 - 5t + 4 \quad \text{and} \quad \chi_{(E, F)}(t) = t^3 - 4t^2 + 5t - 2$$

References: Franco SALIOLA. Lecture notes for Géométrie et combinatoire.

Richard P. STANLEY. An Introduction to Hyperplane Arrangements. §3, 4.