

Index Theorems for Quantum Graphs

J. Phys. A **40** (2007) 14165–14180

S A. FULLING, P. KUCHMENT, & J. H. WILSON*

*Departments of Mathematics and Physics,
Texas A&M University*

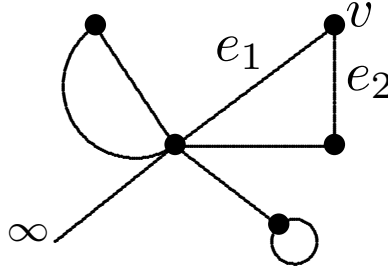
* Undergraduate Research Fellow; now at University of Maryland

CREDITS

- National Science Foundation
- Isaac Newton Institute for Mathematical Sciences, University of Cambridge, Program on Analysis on Graphs and Its Applications, 2007
- Participants there: Jens Bolte, Vadim Kostrykin, Audrey Terras, ...
- Other members of the quantum graph group at TAMU: Gregory Berkolaiko, Jonathan Harrison, Brian Winn

What is a quantum graph?

A quantum graph combines the features of one-dimensional and multidimensional systems.



A quantum graph is a Riemannian 1-complex equipped with a self-adjoint second-order Laplacian operator:

On each edge: $-\frac{d^2}{dx_e^2}u = k^2u \equiv \lambda u.$

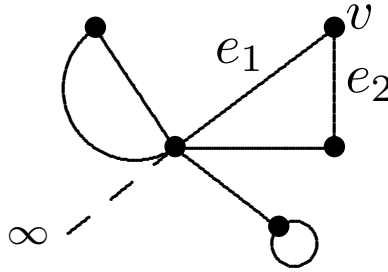
At each vertex: Boundary conditions that make it self-adjoint. *Example:* u is continuous and

$$\sum_e \frac{du}{dx_e} = \alpha_v u(v).$$

Note: This is a *metric graph*, not a *combinatorial graph* where the edges are inert and

$$\Delta u(v) \equiv (\text{const}) u(v) - \sum_{\text{neighbors}} u(v_e).$$

For today: *compact* graphs (finitely many edges, each of finite length). No isolated vertices. Multiple links are allowed, as are loops (tadpoles).



APPLICATIONS OF QUANTUM GRAPHS

1. Modeling thin structures in 3 dimensions (quantum wires)
e.g., Kuchment, *Waves Random Media* **12** (2002) R1
2. Abstract model of quantum chaos
e.g., Kottos & Smilansky, *Phys. Rev. Lett.* **24** (1997) 4794
3. Symbolic dynamics for wave propagation in piecewise homogeneous media
e.g., Dabaghian et al., *Phys. Rev. E* **63** (2001) 066201

4. Lungs, veins, ...
e.g., Carlson, 2005 Snowbird conference (*Contemp. Math.* **415** (2006) 65)
5. Modeling of multidimensional (continuum)
quantum-mechanical systems
 - Melnikov & Pavlov, *J. Math. Phys.* **42** (2001) 1202
 - Exner, Hejčík, & Šeba, *Rep. Math. Phys.* **57** (2006) 445

MORE ABOUT BOUNDARY CONDITIONS

Kostrykin & Schrader (1999): $A\mathbf{u}(v) + B\mathbf{u}'(v) = 0$
with some technical conditions on matrices A and B .

Kuchment (2004): At each vertex v , of degree d_v ,
there are orthogonal projectors P_v and Q_v operating
in \mathbf{C}^{d_v} and a self-adjoint matrix Λ_v operating in the
complementary subspace, $(1 - P_v - Q_v)\mathbf{C}^{d_v}$. (Any of
the three subspaces might be zero.) The functions u in
the operator domain are those members of the Sobolev

space $\bigoplus_e H^2(e)$ that satisfy, at each vertex, boundary conditions consisting of the “Dirichlet part”

$$P_v \mathbf{u}(v) = 0,$$

the “Neumann part”

$$Q_v \mathbf{u}'(v) = 0,$$

and the “Robin part”

$$(1 - P_v - Q_v) \mathbf{u}'(v) = \Lambda_v (1 - P_v - Q_v) \mathbf{u}(v),$$

$u'_e \equiv \frac{du}{dx_e}$ being the derivative along edge e in the

outgoing direction. The domain of $H = -\frac{d^2}{dx_e^2}$ as a quadratic form consists of the functions $u(x_e)$ that belong to the Sobolev space $H^1(e)$ on each edge and satisfy $P_v \mathbf{u}(v) = 0$ (the Dirichlet part of the BC) at each vertex. The Robin matrices Λ_v arise from boundary terms in the quadratic form defining the operator.

Nongeometer's point of view

Each edge has an initial point ($x_e = 0$) and a terminal point ($x_e = L_e$).

$$u'_e(v) = \begin{cases} u'_e(0), & \text{or} \\ -u'_e(L_e), & \end{cases} \quad \text{depending.}$$

Geometer's point of view

u'_e is a one-form (or a vector field). $du_e = \frac{du}{dx_e} dx_e$ is unambiguous. At each vertex we understand $u'_e(v)$ to be the outgoing (from the vertex) derivative.

KIRCHHOFF BOUNDARY CONDITIONS

Dir.: $u_e(v) = \text{same for all } e$ (continuity);

Neu.: $\sum_{e=1}^{d_v} u'_e(v) = 0$ (no net flux);

no Robin part.

Dual (anti-Kirchhoff) boundary conditions

Dir.:
$$\sum_{e=1}^{d_v} w_e(v) = 0 \quad (\text{average value at vertex} = 0);$$

Neu.:

$w'_e(v) = \text{same for all } e \quad (\text{continuity of divergence}).$

These conditions are natural for $w \in \Lambda^1(\Gamma)$, $w' = *d*w \in \Lambda^0(\Gamma)$.

The heat kernel of a quantum graph

J.-P. Roth (1983): For Kirchhoff BC,

$$\begin{aligned} \sum_{n=0}^{\infty} e^{-\lambda_n t} &= \text{Tr } K \equiv \int_{\Gamma} K(t, x, x) dx \\ &= \text{sum over closed paths} = K_1 + K_2 + K_3. \end{aligned}$$

1. Zero length: $K_1 = \frac{L}{\sqrt{4\pi t}}$ (Weyl's law).
 $L \equiv$ total length of Γ .

2. Periodic:
$$K_2 = \frac{1}{\sqrt{4\pi t}} \sum_C \mathcal{A}(C) L(C_p) e^{-L(C)^2/4t}.$$

$L(C), L(C_p) \equiv$ path lengths.

$\mathcal{A}(C) \equiv$ an amplitude you don't want to know.

3. Closed, nonperiodic:

“Ce calcul est un peu plus délicat.”

$$K_3 = \frac{1}{2}(V - E)$$

(rest of the Weyl series; the **only** constant term).

$V \equiv$ number of vertices, $E \equiv$ number of edges.

$V - E$ is

- an integer;
- “topological” (Euler characteristic of a 1-complex).

So what? ...

Let's generalize Gilkey, *Asymptotic Formulae in Spectral Geometry*, which treats this graph: $0 \bullet \text{---} \bullet \pi$

Let $d \equiv \frac{d}{dx}: \Lambda^0(\Gamma) \rightarrow \Lambda^1(\Gamma)$ with Kirchhoff conditions

- Dirichlet part: $u_e(v)$ independent of e ;
- Neumann part: $\sum_e u'_e(v) = 0$.

Then $d^\dagger \equiv -\frac{d}{dx}: \Lambda^1(\Gamma) \rightarrow \Lambda^0(\Gamma)$ with dual conditions

- Dirichlet part: $\sum_e w_e(v) = 0$;
- Neumann part: $w'_e(v)$ independent of e .

$d^\dagger d \equiv H_K = \text{Kirchhoff Laplacian};$

$dd^\dagger \equiv H_A = \text{dual Laplacian}.$

$$d^\dagger d \equiv H_K; \quad dd^\dagger \equiv H_A.$$

(Outer operator on form domain $\oplus_e H^1(e)_{\text{Dir}}$;
 inner operator on operator domain $\oplus_e H^2(e)_{\text{Dir,Neu}}$.)

Let K_K and K_A be the respective heat kernels.

$$\text{Tr } K_K = \frac{L}{\sqrt{4\pi t}} + \frac{1}{2}(V - E) + \dots$$

$$\text{Tr } K_A = \frac{L}{\sqrt{4\pi t}} + \frac{1}{2}(E - V) + \dots$$

There follows:

Index theorem (simplest case)

$$\text{index } d = \text{Tr } K_K - \text{Tr } K_A = V - E = \chi(\Gamma).$$

COROLLARY

Let C be the number of connected components of Γ .
Then

$$\dim \ker d = \dim \ker H_K = C,$$

$$\dim \ker d^\dagger = \dim \ker H_A = E - V + C.$$

In particular, in the connected case

$$\dim \ker d^\dagger = E - V + 1 = r,$$

the rank of the fundamental group. (Number of locally constant anti-Kirchhoff vector fields = number of independent cycles in graph.)

More general boundary conditions

A choice of self-adjoint extension dictates an internal *scattering matrix* $\sigma(k)$ for the graph
(unitary; number of indices = $2E$; $k = \sqrt{\lambda}$).

Theorem (Kostrykin & Schrader; Kuchment): These are equivalent:

- There is no “Robin part” in the boundary conditions: $1 - P_v - Q_v = 0$.
- σ is independent of k (scale invariance).
- $\sigma^2 = I$, so $\sigma = I - 2P$ ($P = \sum P_v =$ orthogonal projection).
- The Laplacian can be factored: $H = A^\dagger A$ where $A = \frac{d}{dx}$ with some vertex conditions.

Theorem (Kostykin, Putthoff & Schrader; Wilson):
For any scale-invariant graph Laplacian H ,

$$\mathrm{Tr} K_H = \frac{L}{\sqrt{4\pi t}} + \frac{1}{4} \mathrm{tr} \sigma + \text{exponential terms.}$$

As before, there is a dual Laplacian (interchanging Dirichlet and Neumann conditions), and its scattering matrix is $-\sigma$. There follows:

INDEX THEOREM (GENERAL CASE)

Define A with the BC defining H and hence A^\dagger with the dual BC. Then $H = A^\dagger A$ and

$$\text{index } A = 2 \text{Tr } K_H .$$

But also ...

Index theorem (rendered trivial by Kuchment)

For any scale-invariant graph Laplacian H ,

$$\text{index } A = E - p,$$

where $p \equiv \dim \text{ran } P$, the number of Dirichlet conditions in the definition of H .

The proof is an elementary exercise in changing the codimension of the domain of a Fredholm operator by a finite amount.

Example:

$$p = \begin{cases} 2E - V & \text{for Kirchhoff,} \\ V & \text{for anti-Kirchhoff.} \end{cases}$$

So

$$\text{index } d = E - p = V - E,$$

$$\text{index } d^\dagger = E - V.$$

The secular determinant

Kottos & Smilansky (1999): The nonzero eigenvalues satisfy a secular equation $\det[U(k) - I] = 0$. But the algebraic multiplicity of $k = 0$ may be greater than its true spectral multiplicity.

Previous methods of determining these multiplicities have proved difficult and error-prone.

COROLLARY OF INDEX THEOREM

Let N_0 and \tilde{N} be the spectral and algebraic multiplicities of $k = 0$ for a scale-invariant graph Laplacian, $A^\dagger A$, and let N_0^* be the spectral multiplicity for the dual Laplacian, AA^\dagger . Then

$$\tilde{N} = 2N_0 - \text{index } A = 2N_0 - E + p,$$

and $\tilde{N} = N_0 + N_0^*$.

Example 1: For H_K , the Laplacian of a connected Kirchhoff graph, $N_0 = 1$ and index $d = V - E$. Therefore, $\tilde{N} = 2 - V + E$, as proved earlier by Kurasov.

Example 2: For a graph consisting of disconnected Neumann edges, one has $N_0 = E$ and $p = 0$, so $\tilde{N} = E$. This is correct, because $k = 0$ appears as a root once for each edge. The dual has disconnected Dirichlet edges and has $N_0^* = 0$ and $p = 2E$. (This pair is the starting point of the elementary Fredholm exercise.)

Conclusions

1. The “topological” term in the heat kernel does have an index interpretation, for scale-invariant boundary conditions.
2. Namely, H has the form $A^\dagger A$, and the index of A can be calculated in three ways:
 - (a) as usual, from $\text{Tr } K_{A^\dagger A} - \text{Tr } K_{AA^\dagger}$.
 - (b) by inspection of $K_{A^\dagger A}$ by itself;
 - (c) just by counting the number of Dirichlet-type boundary conditions.

3. The geometer's viewpoint (one-forms versus functions) is helpful.
4. The algebraic multiplicity of 0 as a root of the secular equation is related to the spectral multiplicities for the Laplacian ($A^\dagger A$) and its dual (AA^\dagger).

A SIMULTANEOUS RELATED PAPER

Olaf Post, First order approach and index theorems for discrete and metric graphs, *Ann. H. Poincaré* **10** (2009) 823–866.

At the Dartmouth conference I learned from Ralf Rueckriemen about an earlier paper:

B. Gaveau and M. Okada, Differential forms and heat diffusion on one-dimensional singular varieties, *Bull. Sci. Math.* **115** (1991) 61–79.

They introduce the first-order formalism and state the simplest index theorem under the name of “Gauss–Bonnet theorem”.