

# ORBIFOLDS

July 16, 2010

# Outline

- 1 Definition and Examples of Orbifolds
- 2 Orbifolds as quotients of manifolds by Lie group actions
- 3 Stratification of orbifolds

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# What is an orbifold?

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An  $n$ -dimensional **orbifold**  $\mathcal{O}$  is a second countable Hausdorff topological space together with a maximal  $n$ -dimensional **orbifold atlas**.

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An **orbifold atlas** is a collection of mutually compatible **orbifold charts** whose images cover  $\mathcal{O}$ .

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# Orbifold charts

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An **orbifold chart** or **uniformizing system**  $(\tilde{U}, \Gamma_U, \pi_U)$  on a connected open set  $U$  is given by

$$\begin{array}{ccc} \tilde{U} & \xrightarrow{\quad} & \Gamma_U \backslash \tilde{U} \xrightarrow{\sim} U \\ & \searrow \pi_U & \nearrow \\ & & \end{array}$$

where

- $\tilde{U}$  is a connected open subset of  $\mathbf{R}^n$
- $\Gamma_U$  is a finite group acting on  $\tilde{U}$  by diffeomorphisms
- $\pi_U : \tilde{U} \rightarrow U$  is a continuous map inducing a homeomorphism from the orbit space  $\Gamma_U \backslash \tilde{U}$  onto  $U$ .

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# Isomorphic charts

## Definition

An isomorphism between two charts  $(\tilde{U}, \Gamma_U, \pi_U)$  and  $(\tilde{U}', \Gamma_{U'}, \pi_{U'})$  on the **same** open set  $U$  is a diffeomorphism  $\phi : \tilde{U} \rightarrow \tilde{U}'$  such that  $\pi_{U'} \circ \phi = \phi \circ \pi_U$ .

$$\begin{array}{ccc}
 \tilde{U} & \xrightarrow{\phi} & \tilde{U}' \\
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Necessarily  $\Gamma_U \simeq \Gamma_{U'}$  and  $\phi$  is equivariant.

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# Automorphisms of charts

## Proposition

*Every automorphism  $(\phi, \Gamma_U)$  of a chart  $(\tilde{U}, \Gamma_U, \pi_U)$  is inner.*

*i.e.,*

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# Injections of charts

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An **injection**  $(\tilde{V}, \Gamma_V, \pi_V) \rightarrow (\tilde{U}, \Gamma_U, \pi_U)$  of charts on  $V \subseteq U$  is an open embedding  $\varphi : \tilde{V} \rightarrow \tilde{U}$  such that the diagram

$$\begin{array}{ccc}
 \tilde{V} & \xrightarrow{\varphi} & \tilde{U} \\
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commutes.

Given such an injection, there exists a monomorphism  $\lambda : \Gamma_V \rightarrow \Gamma_U$  such that  $\varphi \circ \gamma = \lambda(\gamma) \circ \varphi$  for all  $\gamma \in \Gamma_U$ .

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# Induced charts

## Proposition

Given a chart  $(\tilde{U}, \Gamma_U, \pi_U)$  on an open set  $U$  and given a connected open subset  $W \subset U$ , there **exists a unique up to isomorphism** chart  $(\tilde{W}, \Gamma_W, \pi_W)$  on  $W$  that injects into  $(\tilde{U}, \Gamma_U, \pi_U)$ . This is the chart **induced** on  $W$  by  $(\tilde{U}, \Gamma_U, \pi_U)$ .

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# Compatibility of charts

## Definition

Two charts  $(\tilde{U}, \Gamma_U, \pi_U)$  and  $(\tilde{U}', \Gamma_{U'}, \pi_{U'})$  on open subsets  $U$  and  $U'$  are said to be **compatible** if for every  $x \in U \cap U'$ , there exists a neighborhood

$$x \in W \subset U \cap U'$$

such that  $(\tilde{U}, \Gamma_U, \pi_U)$  and  $(\tilde{U}', \Gamma_{U'}, \pi_{U'})$  induce isomorphic charts on  $W$ .

Caution: There's a subtlety here.

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# Good versus Evil

An orbifold is **good** if it is of the form

$$\mathcal{O} = \Gamma \backslash M$$

where  $\Gamma$  is a discrete group acting properly discontinuously on  $M$ .

( $\Gamma$  does *not* have to be finite.)

Otherwise  $\mathcal{O}$  is **bad**.

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# Singular points

## Definition

A point  $x \in \mathcal{O}$  is said to be **singular** if in a chart  $(\tilde{U}, \Gamma_U, \pi_U)$  on a neighborhood  $U$  of  $x$ , the isotropy group

$$\text{Iso}(\tilde{x}) = \{\gamma \in \Gamma_U : \gamma(\tilde{x}) = \tilde{x}\}$$

is non-trivial.

The group  $\text{Iso}(\tilde{x})$  is the abstract isotropy group of  $x$ .

## Exercise

The isotropy group of  $x$  is well-defined (up to isomorphism) independently of the choice of chart.

# Riemannian orbifolds

## Definition

A **Riemannian metric**  $g$  on an orbifold  $\mathcal{O}$  is given by specifying a  $\Gamma_U$ -invariant Riemannian metric  $g_{\tilde{U}}$  on each chart  $(\tilde{U}, \Gamma_U, \pi_U)$  subject to the compatibility condition:  
each injection  $\phi : \tilde{U} \rightarrow \tilde{V}$  of charts is an isometric embedding.

## Theorem

*Every orbifold admits Riemannian metrics.*

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# Geodesic charts

## Definition

We will say that a chart  $(\tilde{U}, \Gamma_U, \pi_U)$  is a **geodesic** chart if  $\tilde{U}$  is a convex geodesic ball.

In this case, the entire group  $\Gamma_U$  fixes the center  $\tilde{x}$  of  $\tilde{U}$ , so  $iso(x) = \Gamma_U$ .

## Remark

The orthogonal action of  $\Gamma_U$  on  $T_{\tilde{x}}(\tilde{U})$  gives a representation of  $iso(x)$  as a subgroup of  $O(n)$ . Up to conjugacy, this subgroup is unique and is even independent of the choice of Riemannian metric on  $\mathcal{O}$ .

Thus “ $iso(x) < O(n)$ ”.

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Thus “ $iso(x) < O(n)$ ”.

# Smooth mappings

## Definition

Let  $\mathcal{O}$  and  $\mathcal{O}'$  be orbifolds. A continuous map  $f : \mathcal{O} \rightarrow \mathcal{O}'$  is said to be a **smooth map** if for each  $p \in \mathcal{O}$ , there exist charts  $(\tilde{U}, \Gamma_U, \pi_U)$  and  $(\tilde{V}, \Gamma_V, \pi_V)$  on neighborhoods  $U$  of  $p$  and  $V$  of  $f(p)$  with  $f(U) \subset V$  and a smooth lift

$$\begin{array}{ccc}
 \tilde{U} & \xrightarrow{\tilde{f}} & \tilde{V} \\
 \pi_U \downarrow & & \downarrow \pi_V \\
 U & \xrightarrow{f} & V
 \end{array}$$

(The lift  $\tilde{f}$  will necessarily be equivariant with respect to  $\Gamma_U$  and  $\Gamma_V$ .)

In particular, a continuous function  $f : \mathcal{O} \rightarrow \mathbf{R}$  is smooth if and only if for each chart  $(\tilde{U}, \Gamma_U, \pi_U)$  on  $\mathcal{O}$  the map  $f \circ \pi_U$  is smooth.

# Orbifold covering maps

A smooth map

$$\varrho : \mathcal{O}' \rightarrow \mathcal{O}$$

is an **orbifold covering map** if each  $x \in \mathcal{O}$  has a chart

$$x \in U \sim \Gamma_U \backslash \tilde{U}$$

such that

$$\varrho^{-1}(U) = \sqcup V_i$$

where

$$V_i \sim \Gamma_i \backslash \tilde{U}$$

with  $\Gamma_i < \Gamma_U$ .

**$k$ -sheeted cover** For regular points  $x$ ,  $\#(\varrho^{-1}(x)) = k$ .

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**$k$ -sheeted cover** For regular points  $x$ ,  $\#(\varrho^{-1}(x)) = k$ .

$$\begin{array}{ccc} & \tilde{U} & \\ & \downarrow & \\ & V_i = \Gamma_i \backslash \tilde{U} & \\ \begin{array}{c} \downarrow \\ e|v_i \end{array} & & \downarrow \\ U = \Gamma \backslash \tilde{U} & & \end{array}$$

## Theorem

Every orbifold  $\mathcal{O}$  has a universal cover  $\tilde{\mathcal{O}}$ . This is a regular cover and  $\mathcal{O} = \Gamma \backslash \tilde{\mathcal{O}}$ . The orbifold  $\mathcal{O}$  is good if and only if  $\tilde{\mathcal{O}}$  is a manifold.

$\Gamma$  is the *fundamental group* of  $\mathcal{O}$ .

## Remark

One can realize the fundamental group as homotopy classes of loops based at a point. However, the notion of smooth map is inadequate for the notion of homotopy. One needs the concept of orbifold morphisms.

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## Theorem

*Every orbifold can be realized as the quotient of a manifold by a proper action of a Lie group.*

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# Strata

## Definition

A smooth **stratification** of a manifold or orbifold  $\mathcal{O}$  is a locally finite partition of  $M$  into locally closed submanifolds, called the **strata**, satisfying:

For each stratum  $N$ , the closure of  $N$  is the union of  $N$  with a collection of lower dimensional strata.

The strata of maximal dimension are open in  $\mathcal{O}$  and their union has full measure in  $\mathcal{O}$ .

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# Orbit types

Consider a smooth action of a Lie group  $G$  on a manifold  $M$ .

## Definition

We say two points in  $M$  have the same  **$G$ -isotropy type** if their isotropy groups are conjugate in  $G$ . The set of all points of a given isotropy type is a union of  $G$ -orbits.

For  $x \in G \backslash M$ , the **isotropy type** of  $x$  is defined to be the isotropy type of the associated  $G$ -orbit in  $M$ .

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## Theorem

*The action of  $G$  gives a stratification of  $M$  in which each stratum is a connected component of the set of all points of a given isotropy type. The closure of a stratum  $N$  is the union of  $N$  with lower dimensional strata with isotropy “containing” that of  $N$ .*

## Theorem

*Let  $\mathcal{O} = G \backslash M$  be an orbifold. The connected components of the sets of points with given isotropy type stratify  $\mathcal{O}$ . The regular points form the strata of maximal dimension. The singular strata have lower dimension.*

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# Orientability

## Definition

A manifold is **orientable** if it admits a covering by of compatibly oriented charts  $(\tilde{U}, \Gamma_U, \pi_U)$  such that the action of  $\Gamma_U$  on  $\tilde{U}$  is orientation-preserving.

## Theorem

*If  $\mathcal{O}$  is orientable, then each singular stratum has co-dimension at least two in  $\mathcal{O}$ .*





